

# **DHANALAKSHMI SRINIVASAN ENGINEERING COLLEGE**

**(An Autonomous Institution, Affiliated to Anna University, Chennai)**

**PERAMBALUR-621212**

**REGULATIONS–2023**

**CHOICE BASED CREDIT SYSTEM**

**M.E. POWER ELECTRONICS AND DRIVES**

**CURRICULUM & SYLLABI**



**DEPARTMENT OF ELECTRICAL AND ELECTRONICS  
ENGINEERING**

**(Applicable to students admitted from the Academic year 2023 – 2024 and subsequently under  
Choice Based Credit System)**

# VISION MISSION OF THE INSTITUTION

## **Vision:**

An active and committed centre of advanced learning focused on research and training in the fields of Engineering, Technology and Management to serve the nation better.

## **Mission:**

- To develop eminent scholar with a lifelong follow up of global standards by offering UG, PG and Doctoral Programmes.
- To pursue Professional and Career growth by collaborating mutually beneficial partnership with industries and higher institutes of research.
- To promote sustained research and training with emphasis on human values and leadership qualities.
- To contribute solutions for the need based issues of our society by proper ways and means as dutiful citizen.

# DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

## About the Department

The Department of Electrical and Electronics Engineering, Dhanalakshmi Srinivasan Engineering College, Perambalur was established in the year 2001 - 2002 and affiliated to ANNA UNIVERSITY, Chennai. Two Post-Graduate programmes M.E. in Power Electronics and Drives during the academic year 2011-2012 and Embedded System Technologies during the academic year 2012-2013 have been introduced. We have a leading edge teaching facility and state-of-the-art laboratory facilities to enhance the learning experience of the students. The department develops the analytical and practical skills of students to serve better industrial, organizational and research set ups.

We provide individual attention and world class quality of education. We have a team of highly qualified, experienced and dedicated faculty to impart quality education to the students. The Department has been accredited by NBA (National Board of Accreditation). The EEE Department has been organizing many Symposiums, Seminars, Conference, Workshop, Guest lectures and the IEEE Chapter.

## Vision:

To infuse technical competencies of Electrical and Electronics Engineering and provide research ambience with values.

## Mission:

- To impart quality education and training in Electrical and Electronics Engineering with an overall background suitable for making a successful Engineer in industry and research or higher education.
- To develop life-long learning skills that allows them to be adaptive and responsive to changes in society, technology and the environment, as well as career demands.
- To provide an accredited dynamic scholarly environment wherein students learn to develop communications and leadership abilities to blossom as a professional.
- To ensure that every graduate is aware of the roles and responsibilities of the professional engineer in society through exposure to ethics, equity, safety and health considerations.

**PROGRAM EDUCATIONAL OBJECTIVES (PEOs):**

PEO 1	To prepare the students for successful career in power electronic industry, research and teaching institutions.
PEO 2	To analyze, design and develop the power electronic converter/drive systems.
PEO 3	To develop the ability to analyze the dynamics in power electronic converters/drives systems and design various controllers to meet the performance criteria.
PEO 4	To design power electronic systems and special electrical machines for efficient extraction and utilization of various renewable energy sources.
PEO 5	To promote student awareness for the lifelong learning and to introduce them to professional ethics

**PROGRAM OUTCOMES (POs)**

PO	Graduate Attribute
PO1	An ability to independently carry out research/investigation and development work to solve practical problems
PO2	An ability to write and present a substantial technical report/document.
PO3	Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program.
PO4	Apply knowledge of basic science and engineering in design and testing of power electronic systems and drives.
PO5	Interact with Industry in a professional and ethical manner to meet the requirements of societal needs and to contribute sustainable development of the society.
PO6	Implement cost effective and cutting edge technologies in power electronics and drives system.

**PEO's – PO's & PSO's MAPPING:**

PEO	PO					
	1	2	3	4	5	6
I	3	3	3	2	2	1
II	2	2	2	3	1	2
III	3	1	1	2	2	3
IV	3	1	2	3	3	2
V	2	1	1	1	3	1

**DHANALAKSHMI SRINIVASAN ENGINEERING COLLEGE (AUTONOMOUS),  
PERAMBALUR – 621 212  
M.E. ELECTRICAL AND ELECTRONICS ENGINEERING  
REGULATIONS – 2023  
CHOICE BASED CREDIT SYSTEM**

**SEMESTER I**

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
<b>THEORY</b>								
1	P23EET11	Applied Mathematics for Power Electronics Engineers	FC	3	1	0	4	4
2	P23EET12	Analysis of Electrical Machines	PCC	3	1	0	4	4
3	P23EET13	Analysis of Power Converters	PCC	3	1	0	4	4
4	P23EET14	Modeling and Design of SMPS	PCC	3	0	0	3	3
5	P23EET15	Research Methodology and IPR	RMC	2	0	0	2	2
6		Professional Elective I	PEC	3	0	0	3	3
7		Audit Course I*	AC	2	0	0	2	0
<b>PRACTICAL</b>								
8	P23EEP11	Power Converters Laboratory	PCC	0	0	3	3	1.5
9	P23EEP12	Analog and Digital Controllers for PE Converters Laboratory	PCC	1	0	3	4	2.5
<b>TOTAL</b>				<b>20</b>	<b>3</b>	<b>6</b>	<b>29</b>	<b>24</b>

**SEMESTER II**

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
<b>THEORY</b>								
1	P23EET21	Analysis of Electrical Drives	PCC	3	1	0	4	4
2	P23EET22	Special Electrical Machines	PCC	3	0	0	3	3
3	P23EET23	Electric Vehicles and Power Management	PCC	3	1	0	4	4
4		Professional Elective II	PEC	3	0	0	3	3
5		Professional Elective III	PEC	3	0	0	3	3
6		Audit course II*	AC	2	0	0	2	0
<b>PRACTICAL</b>								
7	P23EEP21	Power Electronics and Drives Laboratory	PCC	0	0	3	3	1.5
8	P23EEP22	Design Laboratory for Power Electronics Systems	PCC	0	0	3	3	1.5
<b>TOTAL</b>				<b>17</b>	<b>2</b>	<b>6</b>	<b>25</b>	<b>20</b>

**SEMESTER III**

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
<b>THEORY</b>								
1		Professional Elective IV	PEC	3	0	0	3	3
2		Professional Elective V	PEC	3	0	0	3	3
3		Open Elective	OEC	3	0	0	3	3
<b>PRACTICAL</b>								
8	P23EEP31	Project Work I	EEC	0	0	12	12	6
<b>TOTAL</b>				<b>9</b>	<b>0</b>	<b>12</b>	<b>21</b>	<b>15</b>

**SEMESTER IV**

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
<b>PRACTICAL</b>								
1	P23EEP41	Project Work II	EEC	0	0	24	24	12
<b>TOTAL</b>				<b>0</b>	<b>0</b>	<b>24</b>	<b>24</b>	<b>12</b>

**LIST OF OPEN ELECTIVES FOR PG PROGRAMME****SUMMARY**

Sl.No.	Subject Area	Credits per semester				Credits Total
		I	II	III	IV	
1.	FC	4	0	0	0	4
2.	PCC	15	14	0	0	29
3.	PEC	3	6	6	0	15
4.	OEC	0	0	3	0	3
5.	EEC	0	0	6	12	18
6.	RMC	2	0	0	0	2
7.	Non Credit/Audit Course	√	√	0	0	0
	<b>Total</b>	<b>24</b>	<b>20</b>	<b>15</b>	<b>12</b>	<b>71</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To develop the ability to apply the concepts of matrix theory in Electrical Engineering problems.
2. To familiarize the students in the field of differential equations to solve boundary value problems associated with engineering applications.
3. To develop the ability among the students to solve problems using Laplace transform associated with engineering applications.
4. To introduce the effective mathematical tools for the solutions of partial differential equations that model several physical processes and to develop Z transform techniques for discrete time systems
5. To develop the ability among the students to solve problems using Fourier series associated with engineering applications.

**UNIT I      MATRIX THEORY      12**

The Cholesky decomposition - Generalized Eigenvectors - Canonical basis - QR factorization - Singular value decomposition - Pseudo inverses - Least square approximation.

**UNIT II      CALCULUS OF VARIATIONS      12**

Concept of variations and its properties - Euler's theorem - Functional dependent on first and higher order of derivatives - Functionals dependent on functions of several independent variables - Variational problems with moving boundaries - Isoperimetric problems - Direct methods : Rayleigh Ritz method and Kantorovich problems

**UNIT III      LAPLACE TRANSFORM TECHNIQUES FOR PARTIAL DIFFERENTIAL EQUATIONS      12**

Definitions - Properties - Transform error function - Bessel's function - Dirac Delta function - Unit step function - Convolution theorem - Inverse Laplace transform - Complex inversion formula - Solutions to partial differential equations: Heat and Wave equations.

**UNIT IV      Z - TRANSFORM TECHNIQUES FOR PARTIAL DIFFERENTIAL EQUATIONS      12**

Z-transforms - Elementary properties – Convergence of Z-transforms - Initial and final value theorems - Inverse Z - transform (using partial fraction and residues) - Convolution theorem - Formation of difference equations – Solution of difference equations using Z - transforms.

**UNIT V      FOURIER SERIES      12**

Fourier Trigonometric series: Periodic function as power signals - Convergence of series - Even and odd functions : Cosine and sine series - Non periodic function - Extension to other intervals - Power signals : Exponential Fourier series - Parseval's theorem and power spectrum - Eigenvalue problems and orthogonal functions - Regular Sturm –Liouville systems - Generalized Fourier series.

**TOTAL: 60 PERIODS**

## COURSE OUTCOMES:

At the end of the course the students would be able to

- CO1 :** Able to apply the concepts of matrix theory in Electrical Engineering problems.
- CO2 :** Able to solve boundary value problems associated with engineering applications.
- CO3:** Able to solve problems using Laplace transform associated with engineering applications
- CO4:** Use the effective mathematical tools for the solutions of partial differential equations by using Z transform techniques for discrete time systems.
- CO5:** Able to solve problems using Fourier series associated with engineering applications.

## REFERENCE BOOKS:

1. Richard Bronson, MATRIX OPERATION , Schaum's outline series, Second Edition, McGraw Hill, New Delhi , 2011.
2. Elsgolc. L.D., " CALCULUS OF VARIATIONS " , Dover Publications Inc., New York, 2007.
3. SankaraRao. K , INTRODUCTION TO PARTIAL DIFFERENTIAL EQUATIONS , Prentice Hall of India Pvt . Ltd, New Delhi , 1997.
4. Grewal.B.S., “Higher Engineering Mathematics”, Khanna Publishers, New Delhi, 44<sup>th</sup> Edition , 2018.

<b>P23EET12</b>	<b>ANALYSIS OF ELECTRICAL MACHINES</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

## COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To understand the principles of electromechanical energy conversion in electrical machines and to know the dynamic characteristics of DC motors.
2. To study the concepts related with AC machines, magnetic noise and harmonics in rotating electrical machines.
3. To interpret the principles of reference frame theory
4. To study the principles of three phase, doubly fed and ‘n’ phase induction machine in machine variables and reference variables.
5. To understand the principles of three phase, synchronous machine in machine variables and reference variables.

<b>UNIT I</b>	<b>ELECTROMECHANICAL ENERGY CONVERSION and DC MACHINES</b>	<b>12</b>
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Magnetic circuits, permanent magnet, Energy conservation - stored magnetic energy, co-energy - force and torque in singly and doubly excited systems – Elementary DC machine and analysis of steady state operation - Voltage and torque equations – dynamic characteristics - DC motors – Time domain block diagrams - solution of dynamic characteristic by Laplace transformation

<b>UNIT II</b>	<b>AC MACHINES –CONCE</b>	<b>PTS</b>	<b>12</b>
Distributed Windings - Winding Functions - Air-Gap Magnetomotive Force -Rotating MMF - Flux Linkage and Inductance -Resistance -Voltage and Flux Linkage Equations for Distributed Winding Machines--magnetic noise and harmonics in rotating electrical machines. Modeling of ‘n’ phase machine.			

**UNIT III REFERENCE FRAME THEORY****12**

Historical background – phase transformation and commutator transformation – transformation of variables from stationary to arbitrary reference frame – transformation of balanced set-variables observed from several frames of reference

**UNIT IV INDUCTION MACHINES****12**

Three phase induction machine and doubly fed induction machine- equivalent circuit and analysis of steady state operation – free acceleration characteristics – voltage and torque equations in machine variables and arbitrary reference frame variables – analysis of dynamic performance for load torque variations- Transformation theory for ‘n’ phase induction machine.

**UNIT V SYNCHRONOUS MACHINES****12**

Three phase synchronous machine and analysis of steady state operation - voltage and torque equations in machine variables and rotor reference frame variables (Park’s equations) – analysis of dynamic performance for load torque variations –Krons primitive machine

**TOTAL: 60 PERIODS****COURSE OUTCOMES:**

After completion of this course, student will be able to

- CO1 :** Understand the principles of electromechanical energy conversion and characteristics of DC motors
- CO2 :** Know the concepts related with AC machines and modeling of ‘n’ phase machines
- CO3:** Interpret the concepts of reference frame theory.
- CO4:** Apply procedures to develop induction machine model in both machine variable form and reference variable forms
- CO5:** Follow the procedures to develop synchronous machine model in machine variables form and reference variable form.

**TEXT BOOKS:**

1. Stephen D. Umans, “Fitzgerald & Kingsley’s Electric Machinery”, Tata McGraw Hill, 7<sup>th</sup> Edition, 2020
2. Bogdan M. Wilamowski, J. David Irwin, The Industrial Electronics Handbook, Second Edition, Power Electronics and Motor Drives, CRC Press, 2011

**REFERENCE BOOKS:**

1. Paul C. Krause, Oleg Wasynczuk, Scott D. Sudhoff, Steven D. Pekarek, “Analysis of Electric Machinery and Drive Systems”, 3<sup>rd</sup> Edition, Wiley-IEEE Press, 2013.
2. R. Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Pearson Education, 1<sup>st</sup> Imprint, 2015.

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide the mathematical fundamentals necessary for deep understanding of power converter operating modes.
2. To introduce the electrical circuit concepts behind the different working modes of power converters so as to enable deep understanding of their operation.
3. To impart required skills to formulate and design inverters for generic load and for machine loads.
4. To equip with required skills to derive the criteria for the design of power converters starting from basic fundamentals.
5. To inculcate knowledge to perform analysis and comprehend the various operating modes of different configurations of power converters

**UNIT I SINGLE PHASE AC-DC CONVERTER****12**

Static Characteristics of power diode, SCR and GTO, half controlled and fully controlled converters with R-L, R-L-E loads and freewheeling diodes – continuous and discontinuous modes of operation-inverter operation and its limit –Sequence control of converters – performance parameters – effect of source impedance and overlap-reactive power and power balance in converter circuit.

**UNIT II THREE PHASE AC-DC CONVERTER****12**

Half controlled and fully controlled converters with R, R-L, R-L-E loads and freewheeling diodes – inverter operation and its limit – performance parameters – effect of source impedance and overlap-12 pulse converter –Applications - Excitation system, DC drive system.

**UNIT III SINGLE PHASE INVERTERS****12**

Introduction to self-commutated switches : MOSFET and IGBT - Principle of operation of half and full bridge inverters – Performance parameters – Voltage control of single phase inverters using various PWM techniques – various harmonic elimination techniques – Design of UPS - VSR operation

**UNIT IV THREE PHASE INVERTERS****12**

180 degree and 120 degree conduction mode inverters with star and delta connected loads – voltage control of three phase inverters: single, multi pulse, sinusoidal, space vector modulation techniques – VSR operation-Application – Induction heating, AC drive system – Current source inverters.

**UNIT V MODERN INVERTERS****12**

Multilevel concept – diode clamped – flying capacitor – cascaded type multilevel inverters - Comparison of multilevel inverters - application of multilevel inverters – PWM techniques for MLI – Single phase & Three phase Impedance source inverters – Filters.

**TOTAL: 60 PERIODS**

## COURSE OUTCOMES:

After completion of this course, student will be able to

- CO1 :** Acquire and apply knowledge of mathematics in power converter analysis
- CO2 :** Model, analyze and understand power electronic systems and equipments.
- CO3:** Formulate, design and simulate phase controlled rectifiers for generic load and for machine loads
- CO4:** Design and simulate switched mode inverters for generic load and for machine loads
- CO5:** Select device and calculate performance parameters of power converters under various operating modes

## TEXT BOOKS:

1. Rashid M.H., "Power Electronics Circuits, Devices and Applications ", Pearson, fourth Edition, 10<sup>th</sup> Impression 2021.
2. Jai P. Agrawal, "Power Electronics System Theory and Design", Pearson Education, First Edition, 2015

## REFERENCE BOOKS:

1. Bimal.K.Bose "Modern Power Electronics and AC Drives", Pearson Education, Second Edition, 2003
2. Ned Mohan, T.M.Undeland and W.P.Robbins, "Power Electronics: converters, Application and design", 3<sup>rd</sup> edition Wiley, 2007.

**P23EET14**

**MODELING AND DESIGN OF SMPS**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

## COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To inculcate knowledge on steady state analysis of Non-Isolated DC-DC converter
2. To perform steady state analysis of Isolated DC-DC converter
3. To educate on different converter dynamics
4. To impart knowledge on the design of controllers for DC-DC converters
5. To familiarize the design magnetics for SMPS applications

### **UNIT I ANALYSIS OF NON-ISOLATED DC-DC CONVERTERS**

**9**

Buck, Boost, Buck- Boost and Cuk converters: Principles of operation – Continuous conduction mode– Concepts of volt-sec balance and charge balance – Analysis and design based on steady- state relationships – Introduction to discontinuous conduction mode - SEPIC topology - design examples - Applications to Battery operated vehicle, PV system.

### **UNIT II ANALYSIS OF ISOLATED DC-DC CONVERTERS**

**9**

Introduction - classification- forward- flyback- pushpull – half bridge – full bridge topologies- design of SMPS - Applications to Battery operated vehicle.

**UNIT III CONVERTER DYNAMICS**

9

AC equivalent circuit analysis – State space averaging – Circuit averaging – Averaged switch modeling – Transfer function model for buck, boost, buck-boost and cuk converters – Input filters.

**UNIT IV CONTROLLER DESIGN**

9

Review of P, PI, and PID control concepts – gain margin and phase margin – Bode plot based analysis – Design of controller for buck, boost, buck-boost and cuk converters

**UNIT V DESIGN OF MAGNETICS**

9

Basic magnetic theory revision – Inductor design – Design of mutual inductance – Design of transformer for isolated topologies – Ferrite core table and selection of area product – wire table – selection of wire gauge

**TOTAL: 45 PERIODS****COURSE OUTCOMES:**

After completion of this course, student will be able to

- CO1 :** Analyse and design Non-Isolated DC-DC converter
- CO2 :** Analyse and design Isolated DC-DC converter
- CO3:** Derive transfer function of different converters
- CO4:** Design controllers for DC-DC converters
- CO5:** Design magnetics for SMPS application

**TEXT BOOKS:**

1. Robert W. Erickson & Dragon Maksimovic, "Fundamentals of Power Electronics", Third Edition, 2020.
2. Ned Mohan, "Power Electronics: A first course", Wiley, 2011, 1<sup>st</sup> edition.

**REFERENCE BOOKS:**

1. John G. Kassakian, Martin F. Schlecht, George C. Verghese, "Principles of Power Electronics", Pearson, India, New Delhi, 2010
2. Simon Ang and Alejandra Oliva, "Power-Switching Converters", CRC press, 3rd edition, 2011.
3. Philip T Krein, "Elements of Power Electronics", Oxford University Press, 2017.

**P23EET15****RESEARCH METHODOLOGY AND IPR**

L	T	P	C
2	0	0	2

**UNIT I RESEARCH DESIGN**

6

Overview of research process and design, Use of Secondary and exploratory data to answer the research question, Qualitative research, Observation studies, Experiments and Surveys..

**UNIT II DATA COLLECTION AND SOURCES**

6

Measurements, Measurement Scales, Questionnaires and Instruments, Sampling and methods. Data - Preparing, Exploring, examining and displaying.

**UNIT III DATA ANALYSIS AND REPORTING**

6

Overview of Multivariate analysis, Hypotheses testing and Measures of Association. Presenting Insights and findings using written reports and oral presentation.

**UNIT IV INTELLECTUAL PROPERTY RIGHTS**

6

Intellectual Property – The concept of IPR, Evolution and development of concept of IPR, IPR development process, Trade secrets, utility Models, IPR & Bio diversity, Role of WIPO and WTO in IPR establishments, Right of Property, Common rules of IPR practices, Types and Features of IPR Agreement, Trademark, Functions of UNESCO in IPR maintenance.

**UNIT V PATENTS**

9

Patents – objectives and benefits of patent, Concept, features of patent, Inventive step, Specification, Types of patent application, process E-filing, Examination of patent, Grant of patent, Revocation, Equitable Assignments, Licences, Licensing of related patents, patent agents, Registration of patent agents.

**TOTAL: 45 PERIODS**

**TEXT BOOKS:**

1. Cooper Donald R, Schindler Pamela S and Sharma JK, “Business Research Methods”, Tata McGraw Hill Education, 11e (2012).
2. Catherine J. Holland, “Intellectual property: Patents, Trademarks, Copyrights, Trade Secrets”, Entrepreneur Press, 2007.

**REFERENCE BOOKS:**

1. David Hunt, Long Nguyen, Matthew Rodgers, “Patent searching: tools & techniques”, Wiley, 2007.
2. The Institute of Company Secretaries of India, Statutory body under an Act of parliament, “Professional Programme Intellectual Property Rights, Law and practice”, September 2013.

<b>P23EEP11</b>	<b>POWER CONVERTERS LABORATORY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>3</b>	<b>1.5</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide the basic understanding of the dynamic behaviour of the power electronic switches
2. To make the students familiar with the digital processors used in generation of gate pulses for the power electronic switches
3. To make the students acquire knowledge on the design of power electronic circuits and implementing the same using simulation tools
4. To facilitate the students to design gate drive circuits for power converters
5. To provide the fundamentals of DC-AC power converter topologies and analyze the harmonics.

## LIST OF EXPERIMENTS

1. Study of switching characteristics of Power MOSFET & IGBT.
2. Circuit Simulation of Three-phase semi-converter with R, RL & RLE load.
3. Circuit Simulation of Three-phase fully controlled converter with R, RL & RLE load.
4. Circuit Simulation of Three-phase Voltage Source Inverter in 180 and 120 degree mode of conduction.
5. Circuit simulation of Three-phase PWM inverter and study of spectrum analysis for various modulation indices.
6. Simulation of Four quadrant operation of DC Chopper.
7. Generation of Gating pulse using Arduino/Micro Controller/PIC microcontroller for a DC-DC converter and single-phase voltage source inverter.
8. Simulation of a single-phase Z-source inverter with R load.
9. Simulation of three-phase AC voltage Controller with R load.
10. Simulation of a five-level cascaded multilevel inverter with R load.
11. Simulation of a Flyback DC-DC converter.

**TOTAL: 60 PERIODS**

## LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

Sl no	Name of the Equipment	Quantity
1.	Arduino or Micro Controller or PIC microcontroller alongwith interfacing cable	5 Nos
2.	CRO	5 Nos
3.	Regulated Power Supply ( 0-30V, 2A)	5 Nos
4.	Digital Multimeter	5 Nos
5.	Personal Computers	25 Nos
6.	Software ( Any software related to Power Electronics & Drives)	5 License users
7.	Printer	1 No

## COURSE OUTCOMES:

At the end of the course the students would be able to

- CO1 :** Comprehensive understanding on the switching behaviour of Power Electronic Switches
- CO2 :** Comprehensive understanding on mathematical modeling of power electronic system and ability to implement the same using simulation tools
- CO3:** Ability of the student to use arduino/microcontroller for power electronic applications
- CO4:** Ability of the student to design and simulate various topologies of inverters and analyze their harmonic spectrum  
Ability to design and fabricate the gate drive power converter circuits.
- CO5:** Analyze the three-phase controlled rectifiers and isolated DC-DC converters for designing the power supplies

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand the concepts related with analog and digital controllers.
2. To design and understand the op-amp circuits and microcontroller circuits for power electronics.
3. To design and select the appropriate digital controller for power converters along with control strategy

**LIST OF EXPERIMENTS**

1. Amplifiers and buffer design and verification by using Opamp
2. Filter design and verification by using Opamp
3. ON/OFF controller design and verification by using analog circuits
4. Design of Driver Circuit using IR2110
5. Waveform generation by using look up table
6. Generation of PWM gate pulses with duty cycle control using PWM peripheral of microcontroller ( TI-C2000 family/ PIC18)
7. Duty cycle control from IDE
8. Duty Cycle control using a POT connected to ADC peripheral in a standalone mode
9. Generation of Sine-PWM pulses for a single and three phase Voltage Source Inverter with control of modulation index using PWM peripheral of microcontroller (TI C2000 family/PIC 18)
10. Design and testing of signal conditioning circuit to interface voltage/current sensor with microcontroller (TI-C2000 family/ PIC18)
11. Interface Hall effect voltage and current sensor with microcontroller and display the current waveform in the IDE and validate with actual waveform in DSO
12. Design of closed loop P, I and PI controllers using OP-AMP
13. Design of closed loop P, I and PI controllers using TI-C2000 family/ PIC18

**TOTAL: 60 PERIODS**

**LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS**

<b>Sl no</b>	<b>Name of the Equipment</b>	<b>Quantity</b>
1.	Power supply (0-5 V; 10A, 0-30V, 10A)	12 number
2.	DSOs (2/4 channel)	12 number
3.	Desktop multimeters	12 numbers
4.	Function generator	4 numbers
5.	Microcontroller Evaluation board (C2000 family/DSPIC/ARM)	12 numbers
6.	Desktop/Laptops	12 numbers

## **COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Identification of suitable analog and digital controller for the converter design.
- CO2 :** Know the advantages of gate driver, sensing and protection circuits in power converters
- CO3:** Hands on with different controller with strategies for design.
- CO4:** Design and testing the proper driving circuits and protection circuits.
- CO5:** Fabrication of analog and digital controllers for various real time applications.

**P23EET21**

**ANALYSIS OF ELECTRICAL DRIVES**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

## **COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To study and analyse the operation of the converter / chopper fed DC drive, both qualitatively and quantitatively.
2. To analyse and design the current and speed controllers for a closed loop solid state DC motor drive.
3. To understand the drive characteristics for different load torque profiles and quadrants of operation.
4. To understand the speed control of induction motor drive from stator and rotor sides.
5. To study and analyse the operation of VSI & CSI fed induction motor control and pulse width modulation techniques.

### **UNIT I DC MOTORS FUNDAMENTALS AND MECHANICAL SYSTEMS 12**

DC motor- Types, induced emf, speed-torque relations; Speed control – Armature and field speed control; Ward Leonard control – Constant torque and constant horse power operation- Introduction to high speed drives and modern drives. Characteristics of mechanical system– dynamic equations, components of torque, types of load; Requirements of drives characteristics – stability of drives–multi-quadrant operation; Drive elements, types of motor duty and selection of motor rating.

### **UNIT II CONVERTER AND CHOPPER CONTROL 12**

Principle of phase control – Fundamental relations; Analysis of series and separately excited DC motor with single-phase and three-phase converters –performance parameters, performance characteristics. Introduction to time ratio control and frequency modulation; chopper controlled DC motor – performance analysis, multi-quadrant control – Chopper based implementation of braking schemes; Related problems.

### **UNIT III CLOSED LOOP CONTROL 12**

Modeling of drive elements – Equivalent circuit, transfer function of self, separately excited DC motors; Linear Transfer function model of power converters; Sensing and feeds back elements – Closed loop speed control – current and speed loops, P, PI and PID controllers – response comparison. Simulation of converter and chopper fed DC drive.

**UNIT IV VSI AND CSI FED STATOR CONTROLLED INDUCTION MOTOR CONTROL**

**12**

AC voltage controller – six step inverter voltage control-closed loop variable frequency PWM inverter fed induction motor (IM) with braking-CSI fed IM variable frequency motor drives – pulse width modulation techniques – simulation of closed loop operation of stator controlled induction motor drives.

**UNIT V ROTOR CONTROLLED INDUCTION MOTOR DRIVES**

**12**

Static rotor resistance control – injection of voltage in the rotor circuit – static scherbius drives – static and modified Kramer drives – sub-synchronous and super-synchronous speed operation of induction machines – simulation of closed loop operation of rotor controlled induction motor drive.

**TOTAL: 60 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Ability to acquire and apply knowledge of mathematics and converter/machine dynamics in Electrical engineering.
- CO2 :** Ability to formulate, design, simulate power supplies for generic load and for machine loads.
- CO3:** Ability to analyze, comprehend, design and simulate direct current motor based adjustable speed drives.
- CO4:** Ability to analyze, comprehend, design and simulate induction motor based adjustable speed drives.
- CO5:** Ability to design a closed loop motor drive system with controllers for the current and speed control operations.

**TEXT BOOKS:**

1. Gopal K Dubey,“Power Semiconductor controlled Drives”, Prentice Hall Inc., NewYersy, 1989
2. R.Krishnan, “Electric Motor Drives – Modeling, Analysis and Control”,Prentice-Hall of India Pvt. Ltd., New Delhi,2010.
3. Bimal K Bose,“Modern Power Electronics and AC Drives”,Pearson Education Asia2002.

**REFERENCE BOOKS:**

1. Gopal K.Dubey,“Fundamentals of Electrical Drives”,Narosal Publishing House, New Delhi, Second Edition, 2009.
2. Vedam Subramanyam, “Electric Drives – Concepts and Applications”, Tata McGraw- Hill publishing company Ltd., New Delhi, 2002.
3. W.Leonhard, “Control of Electrical Drives”, Narosa Publishing House, 1992.
4. P.C Sen “Thyristor DC Drives”, John wiely and sons, New York, 1981.

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand the working, characteristics and speed control principles of stepper motor.
2. To study the construction, working, characteristics and speed control methods of switched reluctance motors.
3. To know the principle of operation, construction, characteristics and speed control methods for the permanent magnet brushless DC motors.
4. To understand the concepts related with permanent magnet synchronous motors and synchronous reluctance motors.
5. To know the features of axial flux machines and its working principles.

**UNIT I STEPPER MOTORS****9**

Constructional features –Principle of operation –Types – Torque predictions – Linear and Non-linear analysis – Characteristics – Drive circuits–Closed loop control – Applications.

**UNIT II SWITCHED RELUCTANCE MOTORS****9**

Constructional features –Principle of operation- Torque prediction–Characteristics-Power controllers – Control of SRM drive- Speed control-current control-design procedures-Sensorless operation of SRM – Current sensing- rotor position measurement and estimation methods- sensorless rotor position estimation-inductance based estimation –applications.

**UNIT III PERMANENT MAGNET BRUSHLESS DC MOTORS****9**

Fundamentals of Permanent Magnets- Types- Principle of operation- Magnetic circuit analysis EMF and Torque equations- Characteristics- Controller design-Transfer function – Machine, Load and Inverter-Current and Speed Controller.

**UNIT IV PERMANENT MAGNET SYNCHRONOUS MOTORS****9**

Permanent Magnet ac Machines, Machine Configurations, PMSM - Principle of operation – EMF and Torque equations - Phasor diagram - Torque speed characteristics – Modeling and small signal equations- evaluation of control characteristics- design of current and speed controllers- Constructional features, operating principle and characteristics of synchronous reluctance motor.

**UNIT V AXIAL FLUX MACHINES****9**

Axial Flux Permanent Magnet Machines- Comparison with Radial Flux Machines-Development- Geometries, Principle of Operation-Torque production - Applications.  
Axial flux switched reluctance machine- Topologies and Structures -Operating Principles -Output Equation- Applications.

**TOTAL: 45 PERIODS****COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Know the concepts related with stepper motor.
- CO2 :** Understand the working and various characteristics of switched reluctance machines.
- CO3:** Study the working principle and characteristics of permanent magnet brushless

DC motors.

**CO4:** Know the construction, working principles and characteristics of permanent magnet synchronous motor and synchronous reluctance motor.

**CO5:** Understand the features of axial flux machines in comparison with radial flux machines and to know the principles of axial flux machines.

**TEXT BOOKS:**

1. Jacek F. Gieras, Dr. Rong-Jie Wang, Professor Maarten J. Kamper - Axial Flux Permanent Magnet Brushless Machines-Springer Netherlands (2008).
2. Bilgin, Berker\_ Emadi, Ali\_ Jiang, James Weisheng - Switched reluctance motor drives: fundamentals to applications-CRC (2019).

**REFERENCE BOOKS:**

1. Ramu Krishnan - Permanent Magnet Synchronous and Brushless DC Motor Drives -CRC Press, Marcel Applications -CRC Press (2001).
2. T.J.E. Miller, 'Brushless magnet and Reluctance motor drives', Clarendon press, London, 1989.

<b>P23EET23</b>	<b>ELECTRIC VEHICLES AND POWER MANAGEMENT</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand the concept of electric vehicles and its operations
2. To present an overview of Electric Vehicle (EV), Hybrid Electric vehicle (HEV) and their architecture
3. To understand the need for energy storage in hybrid vehicles
4. To provide knowledge about various possible energy storage technologies that can be used in electric vehicles

**UNIT I ELECTRIC VEHICLES AND VEHICLE MECHANICS 12**

Electric Vehicles (EV), Hybrid Electric Vehicles (HEV), Engine ratings- Comparisons of EV with internal combustion Engine vehicles- Fundamentals of vehicle mechanics.

**UNIT II ARCHITECTURE OF EV's AND POWER TRAIN COMPONENTS 12**

Architecture of EV's and HEV's – Plug-n Hybrid Electric Vehicles (PHEV)- Power train components and sizing, Gears, Clutches, Transmission and Brakes.

**UNIT III POWER ELECTRONICS AND MOTOR DRIVES 12**

Electric drive components – Power electronic switches- four quadrant operation of DC drives – Induction motor and permanent magnet synchronous motor-based vector control operation – Switched reluctance motor (SRM) drives- EV motor sizing.

**UNIT IV BATTERY ENERGY STORAGE SYSTEM****12**

Battery Basics- Different types- Battery Parameters-Battery life & safety impacts -Battery modeling-Design of battery for large vehicles.

**UNITV ALTERNATIVE ENERGY STORAGE SYSTEMS****12**

Introduction to fuel cell–Types, Operation and characteristics- proton exchange membrane (PEM) fuel cell for E-mobility–hydrogen storage systems–Super capacitors for transportation applications.

**TOTAL: 60 PERIODS****COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand the concept of electric vehicle and energy storage systems.
- CO2 :** Describe the working and components of Electric Vehicle and Hybrid Electric Vehicle.
- CO3:** Know the principles of power converters and electrical drives.
- CO4:** Illustrate the operation of storage systems such as battery and super capacitors.
- CO5:** Analyze the various energy storage systems based on fuel cells and hydrogen storage.

**TEXT BOOKS:**

1. Iqbal Hussain, “Electric and Hybrid Vehicles: Design Fundamentals, Second Edition” CRC Press, Taylor & Francis Group, Second Edition (2011).
2. Ali Emadi, Mehrdad Ehsani, John M.Miller, “Vehicular Electric Power Systems”, Special Indian Edition, Marcel dekker, Inc 2010.

**REFERENCE BOOKS:**

1. Mehrdad Ehsani, YiminGao, Sebastian E. Gay, Ali Emadi, 'Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design', CRC Press, 2004.
2. Wie Liu, “Hybrid Electric Vehicle System Modeling and Control”,Second Edition, John Wiley & Sons, 2017.

**P23EEP21****POWER ELECTRONICS AND DRIVES  
LABORATORY**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>0</b>	<b>0</b>	<b>3</b>	<b>1.5</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To control the speed of DC motor-based drive system.
2. To conduct load tests in an electrical drive system.
3. To conduct experiments to enhance the understanding of different power electronic controller for motor drive applications.
4. To control the speed of Stepper motor and BLDC motor-based drive systems.
5. To control the speed of an Induction motor and SRM motor-based drive systems.

## LIST OF EXPERIMENTS

1. Simulation of closed loop control of Converter fed DC drive.
2. Speed control of Converter fed DC motor.
3. Speed control of Chopper fed DC motor.
4. Simulation of VSI fed three phase Induction motor drive.
5. V/f control of Three-Phase Induction motor.
6. Micro controller based speed control of Stepper motor.
7. Speed control of BLDC motor.
8. Speed control of BLDC motor.
9. Simulation of Four quadrant operation of three-phase induction motor
10. Voltage Regulation of three-phase Synchronous Generator.
11. AC voltage Controller based speed control of induction motor.

**TOTAL: 45 PERIODS**

## LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

SI NO	Name of the Equipment	Quantity
1.	Fully controlled Converter fed DC motor.	1 NO
2.	Half controlled Converter fed DC motor.	1 NO
3.	Chopper fed DC motor.	1 NO
4.	V/f control of Three-Phase Induction motor.	1 NO
5.	AC voltage Controller based speed control of induction motor.	1 NO
6.	DSP based speed control of SRM motor.	1 NO
7.	Three-phase Synchronous Generator set up to conduct voltage regulation.	1 NO
8.	Micro controller based speed control of Stepper motor.	1 NO
9.	Digital storage oscilloscopes.	5 NO
10.	Computers.	10 NO
11.	Simulation software with minimum 5 user license.	

## COURSE OUTCOMES:

At the end of the course the students would be able to

- CO1 :** Ability to construct the simulation circuit for the closed loop control of drive systems.
- CO2 :** Ability to formulate, design the speed controller for DC motor-based drive system.
- CO3:** Ability to conduct load tests in an electrical drive system.
- CO4:** Ability to formulate, design the speed controller for AC motor-based drive system.
- CO5:** Ability to design the control algorithm for the control of an electrical drive using Microcontroller and Digital signal processor.

<b>P23EEP22</b>	<b>DESIGN LABORATORY FOR POWER ELECTRONICS SYSTEMS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>3</b>	<b>1.5</b>

## COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To design power converter after selecting the suitable component for typical applications
2. To design non-isolated and isolated switching mode regulators
3. To simulate analyse and test different switching mode regulators

## LIST OF EXPERIMENTS

1. Selection and Design of components (Inductor, Capacitor, transformers and devices) for power converters
2. Design and testing of Isolated converter design and verification (100 W)
4. Design and testing of Non-isolated converter design and verification (100 W)
5. Mini Project Demonstration with applications

**TOTAL: 45 PERIODS**

## LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

SI NO	Name of the Equipment	Quantity
1.	Computers.	15
2.	Simulation software.	10 User license
3.	PCB board.	10 Nos.
4.	Inductors, capacitors and transformers for 100 W converter.	10 No Each

## COURSE OUTCOMES:

At the end of the course the students would be able to

- CO1 :** Ability to independently carryout research and development work in power converters.
- CO2 :** Ability to demonstrate a degree of mastery over the design and fabrication of switching regulators.
- CO3:** Ability to apply conceotual basis required for design and testing of various.
- CO4:** Ability to interact with industry to take up problem of societal importance as miniproject designed.
- CO5:** Ability to compare different possible solution to the same practical problem.

**P23EEV11**

**POWER SEMICONDUCTOR DEVICES**

L	T	P	C
3	0	0	3

## COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To understand the concepts related with power switches and its requirements.
2. To know about the developments and characteristics of Silicon Carbide (SiC) and Gallium Nitride (GaN) devices..
3. To understand the working, steady state and switching characteristics of current controlled and voltage controlled silicon devices.
4. To study the working of driving circuits, protection circuits for power devices.
5. To understand the thermal characteristics of power devices and the ability to design heat sink for the power devices.

## UNIT I INTRODUCTION

**9**

Power switching devices overview – Attributes of an ideal switch, application requirements, circuit symbols; Power handling capability – (SOA); Power diodes – Types, forward and reverse characteristics, switching characteristics – rating. Features and Brief History of Silicon Carbide- Promise and Demonstration of SiC Power Devices- Physical Properties of Silicon Carbide devices –Unipolar and Bipolar Diodes- GaN Technology Overview.

**UNIT II CURRENT CONTROLLED DEVICES 9**

BJT's – Construction, static characteristics, switching characteristics; Negative temperature coefficient and second breakdown; - Thyristors – Construction, working, static and transient characteristics, types, series and parallel operation; comparison of BJT and Thyristor – steady state and dynamic models of BJT & Thyristor- Basics of GTO, SiC based Bipolar devices- Applications- Building a GaN Transistor –GaN Transistor Electrical Characteristics

**UNIT III VOLTAGE CONTROLLED DEVICES 9**

Power MOSFETs and IGBTs – Principle of voltage controlled devices, construction, types, static and switching characteristics, steady state and dynamic models of MOSFET and IGBTs – and IGCT. New semiconductor materials for devices – Intelligent power modules- study of modules like APTGT100TL170G, MSCSM70TAM05TPAG. Integrated gate commutated thyristor (IGCT) - SiC based unipolar devices-applications

**UNIT IV DEVICE SELECTION , DRIVING and PROTECTING CIRCUITS 9**

Device selection strategy – On-state and switching losses – EMI due to switching. Necessity of isolation, pulse transformer, optocoupler – Gate drive integrated circuit: Study of Driver IC – IRS2110/2113. SCR, MOSFET, IGBTs and base driving for power BJT. – Over voltage, over current and gate protections; Design of snubbers

**UNIT V THERMAL PROTECTION 9**

Heat transfer – conduction, convection and radiation; Cooling – liquid cooling, vapour – phase cooling; Guidance for heat sink selection – Thermal resistance and impedance –Electrical analogy of thermal components, heat sink types and design – Mounting types- switching loss calculation for power device

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

After completion of this course, student will be able to

- CO1 :** Identification of suitable device for the application.
- CO2 :** Know the advantages of Silicon Carbide devices and Gallium Nitride devices
- CO3:** Understand the principles and characteristics of Silicon devices, Silicon Carbide devices and Gallium Nitride devices.
- CO4:** Design proper driving circuits and protection circuits.
- CO5:** Construct a proper thermal protective devices for power semiconductor devices

**REFERENCE BOOKS:**

1. Rashid M.H., “ Power Electronics Circuits, Devices and Applications “, Pearson, 4<sup>th</sup> Edition, 10<sup>th</sup> Impression 2021.
2. Mohan, Undeland and Robins, “Power Electronics: Converters Applications and Design, Media Enhanced 3<sup>rd</sup> Edition, Wiley, 2007
3. Tsunenobu Kimoto and James A. Cooper , Fundamentals of Silicon Carbide Technology: Growth, Characterization, Devices, and Applications, First Edition., 2014 John Wiley & Sons Singapore Pte Ltd
4. Alex Lidow, Johan Strydom, Michael de Rooij, David Reusch, GaN Transistors for efficient power conversion, Second Edition, Wiley, 2015

<b>P23EEV12</b>	<b>SYSTEM DESIGN USING MICROCONTROLLER</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To get introduced to the fundamentals of microcontroller based system design.
2. To learn I/O and other built-in features available in microcontroller.
3. To know Microcontroller based system design, applications
4. To learn I/O interface in system Design
5. To involve Discussions/ Practice/Exercise onto revising & familiarizing the concepts acquired for improved employability skills

**UNIT I 8051 ARCHITECTURE 9**

Architecture – memory organization – addressing modes – instruction set – Timers – Interrupts – I/O ports, Interfacing I/O Devices – Serial Communication.

**UNIT II 8051 PROGRAMMING 9**

Assembly language programming – Arithmetic Instructions – Logical Instructions – Single bit Instructions – Timer Counter Programming – Serial Communication Programming Interrupt Programming – LCD digital clock/thermometer. Introduction to IDE based assembler programming.

**UNIT III PIC 16 MICROCONTROLLER 9**

Architecture – memory organization – addressing modes – instruction set – PIC programming in Assembly & C – I/O port, Data Conversion, RAM & ROM Allocation, Timer programming, practice in MP-LAB.

**UNIT IV PERIPHERAL OF PIC 16 MICROCONTROLLER 9**

Timers – Interrupts, I/O ports- I2C bus-A/D converter-UART- CCP modules –ADC, DAC and Sensor Interfacing –Flash and EEPROM Memories

**UNIT V SYSTEM DESIGN –CASE STUDY 9**

Interfacing LCD Display – Keypad Interfacing – Generation of Gate signals for converters and Inverters – Motor Control – Controlling DC/ AC appliances – Measurement of frequency- Stand alone Data Acquisition System

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

After completion of this course, student will be able to

- CO1 :** Ability to understand the features of microcontroller 8051
- CO2 :** Ability to write programs using 8051 assemble language, utilizing its build in features
- CO3:** Ability to understand the features of PIC microcontroller.

- CO4:** Ability to use the peripherals built in the PIC microcontroller through programming.
- CO5:** Ability to grasp the interfacing concepts involving in the design of microcontroller based systems.

**TEXT BOOKS:**

1. Kenneth J Ayala, "The 8051 Microcontroller", Thomson press, 2007
2. Muhammad Ali Mazidi, Rolin D. McKinlay, Danny Causey ' PIC Microcontroller and Embedded Systems using Assembly and C for PIC18', Pearson Education 2008

**REFERENCE BOOKS:**

1. Rajkamal, "Microcontrollers Architecture, Programming, Interfacing & System Design, Pearson, 2012.
2. Myke Predko, "Programming and customizing the 8051 microcontroller", Tata McGraw Hill 2001
3. Muhammad Ali Mazidi, Sarmad Naimi, Sepehr Naimi, "The AVR Microcontroller and Embedded Systems' Using Assembly & C, Pearson Education, 2014
4. Muhammad Ali Mazidi, Janice G. Mazidi and Rolin D. McKinlay, 'The 8051 Microcontroller and Embedded Systems' Prentice Hall, 2005.

<b>P23EEV13</b>	<b>ELECTROMAGNETIC FIELD COMPUTATION AND MODELLING</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To refresh the fundamentals of Electromagnetic Field Theory.
2. To provide foundation in formulation and computation of electromagnetic field equations using analytical methods
3. To impart knowledge in the concept of problem formulation and computation of electromagnetic field equations using numerical methods.
4. To compute and analyze the field quantities using FEM.
5. To formulate, solve, analyze and optimize the design of electrical components

**UNIT I INTRODUCTION 9**

Review of basic field theory – Maxwell’s equations – Constitutive relationships and Continuity equations – Laplace, Poisson and Helmholtz equation – principle of energy conversion – force/torque calculation

**UNIT II BASIC SOLUTION METHODS FOR FIELD EQUATIONS 9**

Limitations of the conventional design procedure need for the field analysis based design, problem definition, boundary conditions, solution by analytical methods - direct integration method – variable separable method – method of images.

**UNIT III SOLUTION BY NUMERICAL METHODS** 9  
 Finite Difference Method - Finite Element method – Boundary Elimination method - Variational Formulation – Energy minimization – Discretisation – Shape functions –Stiffness matrix –1D and 2D planar and axial symmetry problems.

**UNIT IV COMPUTATION OF BASIC QUANTITIES USING FEM PACKAGES** 9  
 Basic quantities – Energy stored in Electric Field – Capacitance – Magnetic Field – Linked Flux – Inductance – Force – Torque – Skin effect – Resistance

**UNITV DESIGN APPLICATIONS** 9  
 Design of Insulators –Magnetic actuators – Transformers – Rotating machines.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

After completion of this course, student will be able to

- CO1 :** Explain and interpret the concept of Electromagnetic Field Theory
- CO2 :** Formulate the field problem and apply analytical and numerical method for solving Electromagnetic field problems.
- CO3:** Formulate Finite Element Methodology for solving Electro Magnetic field problem
- CO4:** Estimate the basic Electromagnetic field quantities using FEM.
- CO5:** Design electrical apparatus using FEM

**REFERENCE BOOKS:**

1. Matthew. N.O. Sadiku, “Elements of Electromagnetics”, Seventh Edition, Oxford University Press, First Indian Edition 2018.
2. K.J.Binns, P.J.Lawrenson, C.W Trowbridge, “The analytical and numerical solution of Electric and magnetic fields”, John Wiley & Sons, 1995.
3. Nicola Biyanchi, “Electrical Machine analysis using Finite Elements”, Taylor and Francis Group, CRC Publishers, 2005.
4. Nathan Ida, Joao P.A.Bastos, “Electromagnetics and calculation of fields”, Springer-Verlage, 1997.

<b>P23EEV14</b>	<b>SOFT COMPUTING TECHNIQUES</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

To educate the students on

1. Design of ANN and fuzzy set theory
2. Analysis and implementation of ANN and Fuzzy logic for modeling and control of Non-linear system and to get familiarized with the Matlab toolbox.
3. Impart the knowledge of various optimization techniques and hybrid schemes with the ANFIS tool box.

**UNIT I INTRODUCTION AND ARTIFICIAL NEURAL NETWORKS 9**

Introduction to intelligent systems- Soft computing techniques- Conventional Computing versus Swarm Computing - Classification of meta-heuristic techniques - Properties of Swarm intelligent Systems - Application domain - Discrete and continuous problems - Single objective and multi-objective problems -Neuron- Nerve structure and synapse- Artificial Neuron and its model- activation functions- Neural network architecture- single layer and multilayer feed forward networks- Mc Culloch Pitts neuron model- perceptron model- Adaline and Madaline-multilayer perception model- back propagation learning methods- effect of learning rule coefficient -back propagation algorithm- factors affecting back propagation training-applications.

**UNIT II ARTIFICIAL NEURAL NETWORKS AND ASSOCIATIVE MEMORY 9**

Counter propagation network- architecture- functioning & characteristics of counter Propagation network- Hopfield/ Recurrent network configuration - stability constraints associative memory and characteristics- limitations and applications- Hopfield v/s Boltzman machine- Adaptive Resonance Theory- Architecture- classifications- Implementation and training - Associative Memory.

**UNIT III FUZZY LOGIC SYSTEM 9**

Introduction to crisp sets and fuzzy sets- basic fuzzy set operation and approximate reasoning. Introduction to fuzzy logic modeling and control- Fuzzification inferencing and defuzzification-Fuzzy knowledge and rule bases-Fuzzy modeling and control schemes for nonlinear systems. Self organizing fuzzy logic control- Fuzzy logic control for nonlinear time delay system.

**UNIT IV GENETIC ALGORITHM 9**

Evolutionary programs – Genetic algorithms, genetic programming and evolutionary programming - Genetic Algorithm versus Conventional Optimization Techniques - Genetic representations and selection mechanisms; Genetic operators- different types of crossover and mutation operators - Optimization problems using GA-discrete and continuous - Single objective and multi-objective problems - Procedures in evolutionary programming

**UNITV HYBRID CONTROL SCHEMES 9**

Fuzzification and rule base using ANN–Neuro fuzzy systems-ANFIS – Fuzzy Neuron - Optimization of membership function and rule base using Genetic Algorithm –Introduction to Support Vector Machine- Evolutionary Programming-Particle Swarm Optimization - Case study – Familiarization of NN, FLC and ANFIS Tool Box.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

Ability to

- CO1 :** Understand the basic architectures of NN and Fuzzy sets
- CO2 :** Design and implement ANN architectures, algorithms and know their limitations
- CO3:** Identify and work with different operations on the fuzzy sets.

- CO4:** Develop ANN and fuzzy logic based models and control schemes for non-linear systems.
- CO5:** Understand and explore hybrid control schemes and PSO

**TEXT BOOKS:**

1. Laurene V. Fausett, “Fundamentals of Neural Networks: Architectures, Algorithms And Applications”, Pearson Education.
2. Timothy J. Ross, “Fuzzy Logic with Engineering Applications” Wiley India, 2008.
3. Zimmermann H.J. "Fuzzy set theory and its Applications" Springer international edition, 2011.
4. David E.Goldberg, “Genetic Algorithms in Search, Optimization, and Machine Learning”, Pearson Education, 2009.
5. W.T.Miller, R.S.Sutton and P.J.Webrose, “Neural Networks for Control” MIT Press”, 1996.
6. T. Ross, “Fuzzy Logic with Engineering Applications”, Tata McGraw Hill, New Delhi, 1995.

**P23EEV15**

**SYSTEM THEORY**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

To educate the students on

1. To educate on modelling and representing systems in state variable form.
2. To train on solving linear and non-linear state equations.
3. To illustrate the properties of control system
4. To classify non-linearities and examine stability of systems in the sense of Lyapunov’s theory.
5. To educate on modal concepts, design of state, output feedback controllers and estimators

**UNIT I STATE VARIABLE REPRESENTATION**

**9**

Introduction-Concept of State-Space equations for Dynamic Systems –Time invariance and linearity- Non uniqueness of state model- Physical Systems and State Assignment – free and forced responses- State Diagrams

**UNIT II SOLUTION OF STATE EQUATIONS**

**9**

Existence and uniqueness of solutions to Continuous-time state equations – Solution of Nonlinear and Linear Time Varying State equations – State transition matrix and its properties – Evaluation of matrix exponential- System modes- Role of Eigen values and Eigen vectors.

**UNIT III PROPERTIES OF THE CONTROL SYSTEM**

**9**

Controllability and Observability - Stabilizability and Detectability-Test for Continuous time Systems- Time varying and Time invariant case-Output Controllability-Reducibility-System Realizations.

**UNIT IV NON-LINEARITIES AND STABILITY ANALYSIS****9**

Equilibrium Points-Stability in the sense of Lyapunov-BIBO Stability-Stability of LTI Systems-Types of nonlinearity – Phase plane analysis – Singular points – Limit cycles – Construction of phase trajectories – Describing function method – Derivation of describing functions. Equilibrium Stability of Nonlinear Continuous Time Autonomous Systems – Direct Method of Lyapunov and the Linear Continuous-Time Autonomous Systems- Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems-Krasovskii and Variable-Gradient Method

**UNITV MODAL ANALYSIS****9**

Controllable and Observable Companion Forms – SISO and MIMO Systems – Effect of State Feedback on Controllability and Observability-Pole Placement by State Feedback for both SISO and MIMO Systems-Full Order and Reduced Order Observers..

**TOTAL: 45 PERIODS****COURSE OUTCOMES:**

Ability to

- CO1 :** Understand the concept of State-State representation for Dynamic Systems
- CO2 :** Explain the solution techniques of state equations
- CO3:** Realize the properties of control systems in state space form
- CO4:** Identify non-linearities and evaluate the stability of the system using Lyapunov notion
- CO5:** Perform Modal analysis and design controller and observer in state space form

**REFERENCE BOOKS:**

1. M. Gopal, “Modern Control System Theory”, New Age International, 2005.
2. Z. Bubnicki, ”Modern Control Theory”, Springer, 2005
3. K. Ogatta, “Modern Control Engineering”, PHI, 2002
4. John S. Bay, “Fundamentals of Linear State Space Systems”, McGraw-Hill, 1999

<b>P23EEV21</b>	<b>POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEMS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide knowledge about different types of renewable energy systems.
2. To analyze the various electrical Generators used for the Wind Energy Conversion Systems.
3. To design a power converter used in renewable energy systems such as AC-DC, DC-DC, and AC-AC converters.
4. To understand the importance of standalone, grid-connected, and hybrid operation in renewable energy systems.
5. To analyse various maximum power point tracking algorithms.

**UNIT I INTRODUCTION TO RENEWABLE ENERGY SYSTEMS 9**

Classification of Energy Sources – Importance of Non-conventional energy sources– Advantages and disadvantages of conventional energy sources – Environmental aspects of energy – Impacts of renewable energy generation on the environment – Qualitative study of renewable energy resources: Ocean energy, Biomass energy, Hydrogen energy, - Solar Photovoltaic (PV), Fuel cells: Operating principles and characteristics, Wind Energy: Nature of wind, Types, control strategy, operating area

**UNIT II ELECTRICAL MACHINES FOR WIND ENERGY CONVERSION SYSTEMS (WECS) 9**

Review of reference theory fundamentals –Construction, Principle of operation and analysis: Squirrel Cage Induction Generator (SCIG), Doubly Fed Induction Generator (DFIG) – Permanent Magnet Synchronous Generator (PMSG).

**UNIT III POWER CONVERTERS AND ANALYSIS OF SOLAR PV SYSTEMS 9**

**Power Converters:**Line commutated converters (inversion-mode) – Boost and buck-boost converters- selection of inverter, battery sizing, array sizing.

**Analysis:**Block diagram of the solar PV systems – Types of Solar PV systems: Stand-alone PV systems, Grid integrated solar PV Systems – Grid connection Issues

**UNIT IV POWER CONVERTERS AND ANALYSIS OF WIND SYSTEMS 9**

**Power Converters:**Three-phase AC voltage controllers- AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters, Grid-Interactive Inverters – Matrix converter.

**Analysis:**Stand-alone operation of fixed and variable speed WECS-Grid integrated SCIG and PMSG based WECS.

**UNITV HYBRID RENEWABLE ENERGY SYSTEMS 9**

Need for Hybrid Systems- Range and type of Hybrid systems- Case studies of Diesel-PV, Wind-PV, Microhydel-PV,Biomass-Diesel systems–Maximum Power Point Tracking (MPPT).

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Analyze the impacts of renewable energy technologies on the environment and demonstrate them to harness electrical power.
- CO2 :** Select a suitable Electrical machine for Wind Energy Conversion Systems.
- CO3:** Design the power converters such as AC-DC, DC-DC, and AC-AC converters for Solar energy systems.
- CO4:** Design the power converters such as AC-DC, DC-DC, and AC-AC converters for Wind energy systems.
- CO5:** Interpret the stand-alone, grid-connected, and hybrid renewable energy systems with MPPT.

**TEXT BOOKS:**

1. S.N.Bhadra, D. Kastha, & S. Banerjee “Wind Electrical Systems”, Oxford University Press, 2009
2. Rashid .M. H “Power electronics Hand book”, Academic press, 2<sup>nd</sup> Edition, 2006.

**REFERENCE BOOKS:**

1. Rai. G.D, “Non-conventional energy sources”, Khanna publishers, 2010.
2. Rai. G.D,” Solar energy utilization”, Khanna publishers, 5<sup>th</sup> Edition, 2008.

<b>P23EEV22</b>	<b>MODERN RECTIFIERS AND RESONANT CONVERTERS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To inculcate knowledge on harmonics standards.
2. To impart knowledge on the design power factor correction rectifiers for UPS applications.
3. To familiarize the design resonant converters for SMPS applications.
4. To provide knowledge on dynamic analysis of DC to DC Converters.
5. To introduce the control techniques for control of resonant converters.

<b>UNIT I</b>	<b>POWER SYSTEM HARMONICS &amp; LINE COMMUTATED RECTIFIERS</b>	<b>9</b>
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Average power-RMS value of an AC waveform-Power factor-AC line current harmonic standards IEC 1000-IEEE 519- The Single phase full wave rectifier-Continuous Conduction Mode- Discontinuous Conduction Mode-Single phase Rectifier’s behavior for large value of Capacitance – Minimizing THD for small value of Capacitance- Three phase rectifiers- Continuous Conduction Mode-Discontinuous Conduction Mode- Introduction to Harmonic trap filters.

<b>UNIT II</b>	<b>PULSE WIDTH MODULATED RECTIFIERS</b>	<b>9</b>
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Properties of Ideal rectifiers-Realization of non-ideal rectifier-Single phase converter system incorporating ideal rectifiers-Modeling losses and efficiency in CCM – high quality rectifiers-Boost rectifier-expression for controller duty cycle-expression for DC load current-solution for converter Efficiency.

<b>UNIT III</b>	<b>RESONANT CONVERTERS</b>	<b>9</b>
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Review on Parallel and Series Resonant Switches-Soft Switching- Zero Current Switching – Zero Voltage Switching –Classification of Quasi resonant switches-Zero Current and Zero Voltage Switching of Quasi Resonant Buck converter- Zero Current and Zero Voltage Switching of Quasi Resonant Boost converter: Steady State analysis.

<b>UNIT IV</b>	<b>DYNAMIC ANALYSIS OF SWITCHING CONVERTERS</b>	<b>9</b>
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Review of linear system analysis-State Space Averaging-Basic State Space Average Model-State Space Averaged model for Buck Converter, Boost Converter, Buck Boost Converter and Cuk Converter.

## UNIT V CONTROL OF PWM RECTIFIERS

9

Pulse Width Modulation-Voltage Mode PWM Scheme-Current Mode PWM Scheme- Average current control-Current programmed Control- Hysteresis control- Nonlinear carrier control – Design of Controllers: PI Controller, Variable Structure Controller for source current shaping of PWM rectifiers.

**TOTAL: 45 PERIODS**

### COURSE OUTCOMES:

At the end of the course the students would be able to

- CO1 :** To understand the standards for supply current harmonics and its significance.
- CO2 :** To design power factor correction rectifiers for UPS applications.
- CO3:** To analyse and design the resonant converters.
- CO4:** To derive the state space model of basic and derived DC-DC converters.
- CO5:** To derive the state space model of basic and derived DC-DC converters.

### TEXT BOOKS:

1. John G. Kassakian, Martin F. Schlecht, George C. Verghese, “Principles of Power Electronics”, Pearson, India, New Delhi, 2010.
2. Philip T Krein, “ Elements of Power Electronics”, Oxford University Press,1998.

### REFERENCE BOOKS:

1. Ned Mohan, “Power Electronics: A first course”, John Wiley,2011.
2. IssaBatarseh, Ahmad Harb, “Power Electronics- Circuit Analysis and Design, Second edition,2018.

**P23EEV23**

**ADVANCED POWER CONVERTERS**

L	T	P	C
3	0	0	3

### COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To study the operation of voltage lift circuits.
2. To impart knowledge on the working of super lift circuits.
3. To learn the operation of ultra lift converters and multiple quadrant converters.
4. To provide knowledge on the principle of bidirectional dual active bridge converters.
5. To educate on the working principle of Impedance source converter.

## UNIT I VOLTAGE-LIFT CONVERTERS

9

Introduction- Self-lift and reverse self-lift circuits- Cuk converter, Luo converter and SEPIC converter- continuous and discontinuous conduction mode.-Applications

## UNIT II POSITIVE OUTPUT &NEGATIVE OUTPUT SUPER-LIFT LUO-CONVERTERS

9

Main series, -Elementary Circuit, Re-Lift Circuit, Triple-Lift Circuit, Higher-Order Lift Circuit-. Continuous and discontinuous conduction modes- Applications

**UNIT III      ULTRA LIFT CONVERTERS AND MULTIPLE-QUADRANT      9**  
**OPERATING LUO-CONVERTERS**

Ultra-Lift Luo- Converter- Operation – Continuous and discontinuous conduction Modes of Ultra- Lift Luo-Converter-Instantaneous Values- Multiple quadrant operating Luo Converters- Circuit explanations-Modes of operation- Applications

**UNIT IV      BIDIRECTIONAL DUAL ACTIVE BRIDGE DC–DC CONVERTERS      9**

Application of Bidirectional DC–DC Converter-Classification of Bidirectional DC–DC Converter–Working Principle of Hybrid-Bridge-Based Dual active bridge (DAB) converter- Performance- Voltage mode control- Principle of Dual-Transformer based DAB converter- Three-Level bidirectional DC–DC converter- Applications

**UNIT V      IMPEDANCE SOURCE CONVERTER      9**

Voltage-Fed Z-source inverters–Topologies –Steady state and dynamic model - Current fed Z-source inverter –Topology –Modification and operational principles.Modulation Methods- Sine PWM- SVPWM and Pulse width Amplitude Modulation- Applications

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :**      Understand the working of voltage lift circuits
- CO2 :**      Design the super lift converters
- CO3:**      Understand the working and applications of ultra-lift converters
- CO4:**      Acquire knowledge on working and design of bi-directional DC-DC converters
- CO5:**      Understand the concepts related with impedance source converter

**TEXT BOOKS:**

1. Fang Lin Luo, Hong Ye “Advanced DC/DC Converters”, Second Edition, CRC press, 2018
2. Yushan Liu , Haitham Abu- Rub , BaomingGe , Dr. FredeBlaabjerg , Omar Ellabban , Poh Chiang Loh, “Impedance source power electronic converters”, Wiley IEEE Press, 2016.
3. DeshangSha, GuoXu, “High-Frequency Isolated Bidirectional Dual Active Bridge DC–DC Converters with Wide Voltage Gain”, Springer 2019.

**REFERENCE BOOKS:**

1. Fang Lin Luo, Hong Ye, “Essential DC/DC Converters”, First Edition, CRC, 2005.
2. Fang Lin Luo, Hong Ye, “Power Electronics Advanced Conversion Technologies”, Second Edition, 2018 CRC press.

<b>P23EEV24</b>	<b>CONTROL OF POWER ELECTRONIC CIRCUITS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To inculcate knowledge on the basics of control for power electronic circuits.
2. To illustrate the concepts of feedback controllers for DC-DC converters.
3. To learn about the controller design for AC-DC converter circuits.
4. To impart knowledge on sliding mode control.

5. To equip with required skills to design flatness-based controllers.

**UNIT I CONTROLLER DESIGN FOR BASIC DC-DC CONVERTERS- PART I 9**

Introduction, Review of Linear Control Theory, Linearization of Various Transfer Function Blocks, Feedback Controller Design in Voltage-Mode Control, Peak-Current Mode Control, Feedback Controller Design in DCM.

**UNIT II CONTROLLER DESIGN FOR BASIC DC-DC CONVERTERS - PART II 9**

Introduction, Linear Feedback Control- Pole Placement by Full State Feedback, Pole Placement Based on Observer Design, Reduced Order Observers, Generalized Proportional Integral Controllers- Hamiltonian Systems Viewpoint - Application to power converters.

**UNIT III CONTROLLER DESIGN FOR BASIC AC-DC CONVERTER CIRCUITS 9**

Introduction, Operating Principle of Single-Phase PFCs, Control of PFCs, Designing the Inner Average-Current-Control Loop, Designing the Outer Voltage-Control Loop, Example of Single-Phase PFC Systems.

**UNIT IV SLIDING MODE CONTROL 9**

Introduction, Variable Structure Systems, Control of Single Switch Regulated Systems, Sliding Surfaces, Equivalent Control and the Ideal Sliding Dynamics, Accessibility of the Sliding Surface, Invariance Conditions for Matched Perturbations- Application to power converters.

**UNIT V FLATNESS BASED CONTROL 9**

Flatness, the use of the differential flatness property, Controller development using flatness- Application to power converters.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Design controller for front end power factor corrector circuits.
- CO2 :** Design controllers for UPS application.
- CO3:** Design controllers for AC-DC converters.
- CO4:** Design sliding mode control for power converters.
- CO5:** Design flatness based control for power converters.

**TEXT BOOKS:**

1. HeberttSira-Ramírez and Ramón Silva-Ortigoza, "Control Design Techniques in Power Electronics Devices " Springer-Verlag London Limited 2006
2. Ned Mohan, "Power Electronics: A First Course", Johnwiley, 2011
3. Marian K. Kazimierczuk and AgasthyaAyachit, "Laboratory Manual for Pulse-Width Modulated DC– DC Power Converters", Wiley 2016

**REFERENCE BOOKS:**

1. FarzinAsadi and Kei Eguchi, Morgan & Claypool, "Dynamics and Control of DC-DC Converters", 2018.
2. Andre Kislovski, "Dynamic Analysis of Switching-Mode DC/DC Converters" ,Springer 1991.
3. Azar, Ahmad Taher, Zhu, Quannmin," Advances and Applications in sliding mode control systems" Springer, 2015.
4. Levine, Jean, "Analysis and control of Non-linear systems A flatness-based approach" Springer, 2009.

**P23EEV25****ENERGY STORAGE TECHNOLOGIES**

L	T	P	C
3	0	0	3

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand the various types of energy storage Technologies.
2. To analyze thermal storage system.
3. To analyze different battery storage technologies.
4. To analyze the thermodynamics of Fuel Cell.
5. To study the various applications of energy storage systems.

**UNIT I INTRODUCTION****9**

Necessity of energy storage—types of energy storage—energy storage technologies – Applications.

**UNIT II THERMAL STORAGE SYSTEM****9**

Thermal storage—Types—Modeling of thermal storage units— Simple water and rock bed storage system—Pressurized water storage system—Modelling of phase change storage system—Simple units, Packed bed storage units-Modelling using porous medium approach.

**UNIT III ELECTRICAL ENERGY STORAGE****9**

Fundamental concept of batteries—Measuring of battery performance, charging and dis charging of a battery, storage density, energy density, and safety issues-Types of batteries:—Lead Acid, Nickel-Cadmium, Zinc-Manganese dioxide-Mathematical Modelling for Lead Acid Batteries – Flow Batteries.

**UNIT IV FUEL CELL****9**

Fuel Cell – History of Fuel cell, Principles of Electrochemical storage – Types: Hydrogen oxygen cells, Hydrogen air cell, Hydrocarbon air cell, Alkaline fuel cell -Detailed analysis – Advantages and disadvantages –Fuel Cell Thermodynamics.

**UNIT V ALTERNATE ENERGY STORAGE TECHNOLOGIES****9**

Flywheel, Super capacitors, Principles & Methods – Applications, Compressed air Energy storage, Concept of Hybrid Storage – Applications, Pumped Hydro Storage – Applications.

**TOTAL: 45 PERIODS**

## **COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand the physics of energy storage.
- CO2 :** Model the different energy technologies.
- CO3:** Recognize the applications of various techniques.
- CO4:** Design and analyze the energy storage technologies.
- CO5:** Select and apply the appropriate technique based on the application.

## **TEXT BOOKS:**

1. James Larminie and Andrew Dicks, 'Fuel cell systems Explained', Wiley publications, 2003.
2. Lunardini V.J, "Heat Transfer in Cold Climates", John Wiley and Sons 1981.

## **REFERENCE BOOKS:**

1. Jiujun Zhang (Editor), Lei Zhang (Editor), Hansan Liu (Editor), Andy Sun (Editor), Ru-Shi Liu (Editor), "Electrochemical technologies for energy storage and conversion", Two Volume Set, Wiley publications, 2012.
2. Schmidt, F.W. and Willmott, A.J., "Thermal Storage and Regeneration", Hemisphere Publishing Corporation, 1981.

**P23EEV26**

**POWER QUALITY**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

## **COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide knowledge about various power quality issues.
2. To understand the concept of power and power factor in single phase and three phase systems supplying nonlinear loads.
3. To equip with required skills to design conventional compensation techniques for power factor correction and load voltage regulation.
4. To introduce the control techniques for the active compensation.
5. To understand the mitigation techniques using custom power devices such as DSTATCOM, DVR & UPQC.

### **UNIT I INTRODUCTION**

**9**

Introduction – Characterization of Electric Power Quality: Transients, short duration and long duration voltage variations, Voltage imbalance, waveform distortion, Voltage fluctuations, Power frequency variation, Power acceptability curves – power quality problems: poor load power factor, Non-linear and unbalanced loads, DC offset in loads, Notching in load voltage, Disturbance in supply voltage – Power quality standards.

### **UNIT II ANALYSIS OF SINGLE PHASE AND THREE PHASE SYSTEM**

**9**

Single phase linear and non-linear loads – single phase sinusoidal, non-sinusoidal source – supplying linear and nonlinear loads – three phase balanced system – three phase unbalanced system – three phase unbalanced and distorted source supplying non-linear loads – concept of power factor – three phase- three wire – three phase - four wire system.

**UNIT III CONVENTIONAL LOAD COMPENSATION METHODS 9**

Principle of load compensation and voltage regulation – classical load balancing problem : open loop balancing – closed loop balancing, current balancing – harmonic reduction and voltage sag reduction– analysis of unbalance – instantaneous of real and reactive powers – Extraction of fundamental sequence component from measured.

**UNIT IV LOAD COMPENSATION USING DSTATCOM 9**

Compensating single – phase loads – Ideal three phase shunt compensator structure – generating reference currents using instantaneous PQ theory – Instantaneous symmetrical components theory – Generating reference currents when the source is unbalanced –Realization and control of DSTATCOM – DSTATCOM in Voltage control mode.

**UNIT V SERIES COMPENSATION OF POWER DISTRIBUTION SYSTEM 9**

Rectifier supported DVR – DC Capacitor supported DVR – DVR Structure – Voltage Restoration – Series Active Filter – Unified Power Quality Conditioner.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** comprehend the consequences of Power Quality issues.
- CO2 :** conduct harmonic analysis of single phase and three phase systems supplying non-linear loads
- CO3:** Design passive filter for load compensation.
- CO4:** Design active filters for load compensation.
- CO5:** understand the mitigation techniques using custom power devices such as distribution static compensator (DSTATCOM), dynamic voltage restorer (DVR) & UPQC.

**TEXT BOOKS:**

1. Arindam Ghosh and Gerard Ledwich “Power Quality Enhancement Using Custom Power Devices”, Kluwer Academic Publishers, First Edition, 2002
2. G.T.Heydt, “Electric Power Quality”, Stars in a Circle Publications, Second Edition, 1994

**REFERENCE BOOKS:**

1. R.C.Duggan “Electric Power Systems Quality”, Tata MC Graw Hill Publishers, Third Edition, 2012.
2. Arrillaga “Power System Harmonics”, John Wiley and Sons, 2003.
3. Derek A.Paice “Power Electronic Converter Harmonics” IEEE Press, 1995.

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand various representation methods of DSP system.
2. To provide insight about different DSP algorithms.
3. To familiarize the various architectures of DSP system.
4. To perform analysis of DSP architectures and to learn the implementation of DSP system in programmable hardware.
5. To learn the details of DSP system interfacing with other peripherals.

**UNIT I REPRESENTATION OF DSP SYSTEM 9**

Single Core and Multicore, Architectural requirement of DSPs - high throughput, low cost, low power, small code size, embedded applications. Representation of digital signal processing systems-block diagrams, signal flow graphs, data-flow graphs, dependence graphs. Techniques for enhancing computational throughput - parallelism and pipelining.

**UNIT II DSP ALGORITHMS 9**

DSP algorithms - Convolution, Correlation, FIR/IIR filters, FFT, adaptive filters, sampling rate converters, DCT, Decimator, Expander and Filter Banks. DSP applications. Computational characteristics of DSP algorithms and applications, Numerical representation of signals-word length effect and its impact, Carry free adders, Multiplier.

**UNIT III SYSTEM ARCHITECTURE 9**

Introduction, Basic Architectural Features, DSP Computational Building Blocks, Bus Architecture and Memory, Data Addressing Capabilities, Address Generation Unit, Programmability and Program Execution, Features for External Interfacing. VLIW architecture. Basic performance issue in pipelining, Simple implementation of MIPS, Instruction Level Parallelism, Dynamic Scheduling, Dynamic Hardware Prediction, Memory hierarchy. Study of Fixed point and floating point DSP architectures

**UNIT IV ARCHITECTURE ANALYSIS ON PROGRAMMABLE HARDWARE 9**

Analysis of basic DSP Architectures on programmable hardware. Algorithms for FIR, IIR, Lattice filter structures, architectures for real and complex fast Fourier transforms, 1D/2D Convolutions, Winograd minimal filtering algorithm. FPGA: Architecture, different sub-systems, design flow for DSP system design, mapping of DSP algorithms onto FPGA.

**UNIT V SYSTEM INTERFACING**

Examples of digital signal processing algorithms suitable for parallel architectures such as GPUs and multiGPUs. Interfacing: Introduction, Synchronous Serial Interface CODEC, A CODEC Interface Circuit, ADC interface.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Evaluate the DSP system using various methods.  
**CO2 :** Design algorithm suitable for different DSP applications.

- CO3:** Explain various architectures of DSP system.
- CO4:** Implement DSP system in programmable hardware.
- CO5:** Build interfacing of DSP system with various peripherals.

**TEXT BOOKS:**

1. Sen M Kuo, Woon Seng S Gan, Digital Signal Processors.
2. Digital Signal Processing and Application with C6713 and C6416 DSK, Rulph Chassaing, Worcester Polytechnic Institute, A Wiley Interscience Publication.

**REFERENCE BOOKS:**

1. Architectures for Digital Signal Processing, Peter Pirsch John Weily, 2007.
2. DSP Processor and Fundamentals:Architecture and Features. Phil Lapsley,JBier, AmitSohan, Edward A Lee; Wiley IEEE Press.

<b>P23EEV28</b>	<b>MACHINE LEARNING AND DEEP LEARNING</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. Understanding about the learning problem and algorithms.
2. Providing insight about neural networks.
3. Introducing the machine learning fundamentals and significance.
4. Enabling the students to acquire knowledge about pattern recognition.
5. Motivating the students to apply deep learning algorithms for solving real life problems.

**UNIT I LEARNING PROBLEMS AND ALGORITHMS 9**

Various paradigms of learning problems, Supervised, Semi-supervised and Unsupervised algorithms

**UNIT II NEURAL NETWORKS 9**

Differences between Biological and Artificial Neural Networks - Typical Architecture, Common Activation Functions, Multi-layer neural network, Linear Separability, Hebb Net, Perceptron, Adaline, Standard Back propagation Training Algorithms for Pattern Association - Hebb rule and Delta rule, Hetero associative, Auto associative, Kohonen Self Organising Maps, Examples of Feature Maps, Learning Vector Quantization, Gradient descent, Boltzmann Machine Learning.

**UNIT III MACHINE LEARNING – FUNDAMENTALS & FEATURE SELECTIONS & CLASSIFICATIONS 9**

Classifying Samples: The confusion matrix, Accuracy, Precision, Recall, F1- Score, the curse of dimensionality, training, testing, validation, cross validation, overfitting, under-fitting the data, early stopping, regularization, bias and variance. Feature Selection, normalization, dimensionality reduction, Classifiers: KNN, SVM, Decision trees, Naïve Bayes, Binary classification, multi class classification, clustering.

**UNIT IV DEEP LEARNING: CONVOLUTIONAL NEURAL NETWORKS 9**

Feed forward networks, Activation functions, back propagation in CNN, optimizers, batch normalization, convolution layers, pooling layers, fully connected layers, dropout, Examples of CNNs.

**UNIT V DEEP LEARNING: RNNs, AUTOENCODERS AND GANS 9**

State, Structure of RNN Cell, LSTM and GRU, Time distributed layers, Generating Text, Autoencoders: Convolutional Autoencoders, Denoising autoencoders, Variational autoencoders, GANs: The discriminator, generator, DCGANs

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Illustrate the categorization of machine learning algorithms.
- CO2 :** Compare and contrast the types of neural network architectures, activation functions.
- CO3:** Acquaint with the pattern association using neural networks.
- CO4:** Elaborate various terminologies related with pattern recognition and architectures of convolutional neural networks.
- CO5:** Construct different feature selection and classification techniques and advanced neural network architectures such as RNN, Autoencoders, and GANs.

**TEXT BOOKS:**

1. J.S.R.Jang, C.T.Sun, E.Mizutani, Neuro Fuzzy and Soft Computing - A Computational Approach to Learning and Machine Intelligence, 2012, PHI learning.
2. Deep Learning, Ian Good fellow, YoshuaBengio and Aaron Courville, MIT Press, ISBN: 9780262035613, 2016.

**REFERENCE BOOKS:**

1. The Elements of Statistical Learning. Trevor Hastie, Robert Tibshirani and Jerome Friedman. Second Edition 2009.
2. Pattern Recognition and Machine Learning. Christopher Bishop. Springer 2006.

**P23EEV29**

**IoT FOR SMART SYSTEMS**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To study about **Internet of Things** technologies and its role in real time applications.
2. To introduce the infrastructure required for IoT.
3. To familiarize the accessories and communication techniques for IoT.
4. To provide insight about the embedded processor and sensors required for IoT.
5. To familiarize the different platforms and Attributes for IoT.

<b>UNIT I</b>	<b>INTRODUCTION TO INTERNET OF THINGS</b>	<b>9</b>
Overview, Hardware and software requirements for IOT, Sensor and actuators, Technology drivers, Business drivers, Typical IoT applications, Trends and implications.		
<b>UNIT II</b>	<b>IOT ARCHITECTURE</b>	<b>9</b>
IoT reference model and architecture -Node Structure - Sensing, Processing, Communication, Powering, Networking - Topologies, Layer/Stack architecture, IoT standards, Cloud computing for IoT, Bluetooth, Bluetooth Low Energy beacons.		
<b>UNIT III</b>	<b>PROTOCOLS AND WIRELESS TECHNOLOGIES FOR IOT PROTOCOLS</b>	<b>9</b>
NFC, SCADA and RFID, Zigbee MIPI,M-PHY,UniPro,SPMI,SPI,M-PCIe GSM,CDMA, LTE, GPRS,Small cell. <b>Wireless technologies for IoT:</b> WiFi (IEEE 802.11), Bluetooth/Bluetooth Smart, ZigBee/ZigBee Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems-Recent trends.		
<b>UNIT IV</b>	<b>IOT PROCESSORS</b>	<b>9</b>
<b>Services/Attributes:</b> Big-Data Analytics for IOT, Dependability,Interoperability,Security, Maintainability. <b>Embedded processors for IOT:</b> Introduction to Python programming-Building IOT with RASPERRY PI and Arduino		
<b>UNIT V</b>	<b>CASE STUDIES</b>	<b>9</b>
Industrial IoT,Home Automation, smart cities, Smart Grid, connected vehicles, electric vehicle charging, Environment, Agriculture, Productivity Applications, IOT Defense		

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Analyze the concepts of IoT and its present developments
- CO2 :** Compare and contrast different platforms and infrastructures available for IoT
- CO3:** Explain different protocols and communication technologies used in IoT
- CO4:** Analyze the big data analytic and programming of IoT
- CO5:** Implement IoT solutions for smart applications

**TEXT BOOKS:**

1. ArshdeepBahga and VijaiMadiseti : A Hands-on Approach “Internet of Things”,Universities Press 2015.
2. Oliver Hersent , David Boswarthick and Omar Elloumi “ The Internet of Things”, Wiley,2016.

**REFERENCE BOOKS:**

1. Samuel Greengard, “ The Internet of Things”, The MIT press, 2015.
2. Adrian McEwen and Hakim Cassimally“Designing the Internet of Things “Wiley,2014.





**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Describe the context and principles of IWRM; Compare the conventional and integrated ways of water management.
- CO2 :** Select the best economic option among the alternatives; illustrate the pros and cons of PPP through case studies.
- CO3:** Apply law and governance in the context of IWRM.
- CO4:** Discuss the linkages between water-health; develop a HIA framework.
- CO5:** Analyse how the virtual water concept pave way to alternate policy options

**TEXT BOOKS:**

1. Cech Thomas V., Principles of water resources: history, development, management and policy. John Wiley and Sons Inc., New York. 2003.
2. Mollinga .P. etal “ Integrated Water Resources Management”, Water in South Asia Volume I, Sage Publications, 2006.

**REFERENCE BOOKS:**

1. Technical Advisory Committee, Integrated Water Resources management, Technical Advisory Committee Background Paper No: 4. Global water partnership, Stockholm, Sweden. 2002.
2. Technical Advisory Committee, Dublin principles for water as reflected in comparative assessment of institutional and legal arrangements for Integrated Water Resources Management, Technical Advisory Committee Background paper No: 3. Global water partnership, Stockholm, Sweden. 1999.
3. Technical Advisory Committee, Effective Water Governance”. Technical Advisory Committee Background paper No: 7. Global water partnership, Stockholm, Sweden, 2003

**P23PEO02**

**WATER, SANITATION AND HEALTH**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. Understand the accelerating health impacts due to the present managerial aspects and initiatives in water and sanitation and health sectors in the developing scenario

**UNIT I FUNDAMENTALS WASH**

**9**

Meanings and Definition: Safe Water- Health, Nexus: Water- Sanitation - Health and Hygiene – Equity issues-Water security - Food Security. Sanitation And Hygiene (WASH) and Integrated Water Resources Management (IWRM) - Need and Importance of WASH.



2002: 91–98. doi: 10.1002/tl.83Improving the Environment for learning: An Expanded Agenda

3. National Research Council. *Global Issues in Water, Sanitation, and Health: Workshop Summary*. Washington, DC: The National Academies Press, 2009.

#### REFERENCE BOOKS:

1. Sen, Amartya 1997. *On Economic Inequality*. Enlarged edition, with annex by James Foster and Amartya Sen, Oxford: Clarendon Press, 1997.
2. *Intersectoral Water Allocation Planning and Management*, 2000, World Bank Publishers [www.Amazon.com](http://www.Amazon.com)
3. *Third World Network.org* ([www.twn.org](http://www.twn.org)).

<b>P23PEO03</b>	<b>PRINCIPLES OF SUSTAINABLE DEVELOPMENT</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

#### COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To impart knowledge on environmental, social and economic dimensions of sustainability and the principles evolved through landmark events so as to develop an action mindset for sustainable development.

#### **UNIT I SUSTAINABILITY AND DEVELOPMENT CHALLENGES 9**

Definition of sustainability – environmental, economical and social dimensions of sustainability - sustainable development models – strong and weak sustainability – defining development- millennium development goals – mindsets for sustainability: earthly, analytical, precautionary, action and collaborative– syndromes of global change: utilisation syndromes, development syndromes, and sink syndromes – core problems and cross cutting Issues of the 21 century - global, regional and local environmental issues – social insecurity - resource degradation –climate change – desertification.

#### **UNIT II PRINCIPLES AND FRAME WORK 9**

History and emergence of the concept of sustainable development - our common future - Stockholm to Rio plus 20– Rio Principles of sustainable development – Agenda 21 natural step- peoples earth charter – business charter for sustainable development –UN Global Compact - Role of civil society, business and government – United Nations’ 2030 Agenda for sustainable development – 17 sustainable development goals and targets, indicators and intervention areas.

#### **UNIT III SUSTAINABLE DEVELOPMENT AND WELLBEING 9**

The Unjust World and inequities - Quality of Life - Poverty, Population and Pollution - Combating Poverty - - Demographic dynamics of sustainability - Strategies to end Rural and Urban Poverty and Hunger – Sustainable Livelihood Framework- Health, Education and

Empowerment of Women, Children, Youth, Indigenous People, Non-Governmental Organizations, Local Authorities and Industry for Prevention, Precaution , Preservation and Public participation

**UNIT IV SUSTAINABLE SOCIO-ECONOMIC SYSTEMS 9**

Sustainable Development Goals and Linkage to Sustainable Consumption and Production – Investing in Natural Capital- Agriculture, Forests, Fisheries - Food security and nutrition and sustainable agriculture- Water and sanitation - Biodiversity conservation and Ecosystem integrity – Ecotourism - Sustainable Cities – Sustainable Habitats- Green Buildings - Sustainable Transportation — Sustainable Mining - Sustainable Energy– Climate Change – Mitigation and Adaptation - Safeguarding Marine Resources - Financial Resources and Mechanisms

**UNITV ASSESSING PROGRESS AND WAY FORWARD 9**

Nature of sustainable development strategies and current practice- Sustainability in global, regional and national context –Approaches to measuring and analysing sustainability– limitations of GDP- Ecological Footprint- Human Development Index- Human Development Report – National initiatives for Sustainable Development - Hurdles to Sustainability - Science and Technology for sustainable development –Performance indicators of sustainability and Assessment mechanism – Inclusive Green Growth and Green Economy – National Sustainable Development Strategy Planning and National Status of Sustainable Development Goals

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Explain and evaluate current challenges to sustainability, including modern world social, environmental, and economic structures and crises.
- CO2 :** Identify and critically analyze the social environmental, and economic dimensions of sustainability in terms of UN Sustainable development goals
- CO3:** Develop a fair understanding of the social, economic and ecological linkage of Human well being, production and consumption
- CO4:** Evaluate sustainability issues and solutions using a holistic approach that focuses on connections between complex human and natural systems.
- CO5:** Integrate knowledge from multiple sources and perspectives to understand environmental limits governing human societies and economies and social justice dimensions of sustainability

**TEXT BOOKS:**

1. Tom Theis and Jonathan Tomkin, Sustainability: A Comprehensive Foundation, Rice University, Houston, Texas, 2012
2. A guide to SDG interactions:from science to implementation, International Council for Science, Paris,2017

## REFERENCE BOOKS:

1. Karel Mulder, Sustainable Development for Engineers - A Handbook and Resource Guide, Rouldege Taylor and Francis, 2017.
2. The New Global Frontier - Urbanization, Poverty and Environment in the 21st Century - *George Martine, Gordon McGranahan, Mark Montgomery and Rogelio Fernández-Castilla*, IIED and UNFPA, Earthscan, UK, 2008
3. Nolberto Munier, Introduction to Sustainability: Road to a Better Future, Springer, 2006
4. Barry Dalal Clayton and Stephen Bass, Sustainable Development Strategies- a resource book”, Earthscan Publications Ltd, London, 2002.

**P23PEO04**

**ENVIRONMENTAL IMPACT ASSESSMENT**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

## COURSE OBJECTIVES

The main learning objective of this course is to prepare the students for:

1. To make the students to understand environmental clearance, its legal requirements and to provide knowledge on overall methodology of EIA, prediction tools and models, environmental management plan and case studies.

### **UNIT I INTRODUCTION**

**9**

Historical development of Environmental Impact Assessment (EIA). Environmental Clearance- EIA in project cycle. legal and regulatory aspects in India – types and limitations of EIA –EIA process- screening – scoping - terms of reference in EIA- setting – analysis – mitigation. Cross sectoral issues –public hearing in EIA- EIA consultant accreditation.

### **UNIT II IMPACT IDENTIFICATION AND PREDICTION**

**9**

Matrices – networks – checklists – cost benefit analysis – analysis of alternatives – expert systems in EIA. prediction tools for EIA – mathematical modeling for impact prediction – assessment of impacts – air – water – soil – noise – biological — cumulative impact assessment

### **UNIT III SOCIO-ECONOMIC IMPACT ASSESSMENT**

**9**

Socio-economic impact assessment - relationship between social impacts and change in community and institutional arrangements. factors and methodologies- individual and family level impacts. communities in transition-rehabilitation

### **UNIT IV EIA DOCUMENTATION AND ENVIRONMENTAL MANAGEMENT PLAN**

**9**

Environmental management plan - preparation, implementation and review – mitigation and rehabilitation plans – policy and guidelines for planning and monitoring programmes – post project audit – documentation of EIA findings – ethical and quality aspects of environmental impact assessment

### **UNIT V CASE STUDIES**

**9**

Mining, power plants, cement plants, highways, petroleum refining industry, storage & handling of hazardous chemicals, common hazardous waste facilities, CETPs, CMSWMF, building and construction projects

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand need for environmental clearance, its legal procedure, need of EIA, its types, stakeholders and their roles
- CO2 :** Understand various impact identification methodologies, prediction techniques and model of impacts on various environments
- CO3:** Understand relationship between social impacts and change in community due to development activities and rehabilitation methods
- CO4:** Document the EIA findings and prepare environmental management and monitoring plan
- CO5:** Identify, predict and assess impacts of similar projects based on case studies

**TEXT BOOKS:**

1. EIA Notification 2006 including recent amendments, by Ministry of Environment, Forest and Climate Change, Government of India
2. Sectoral Guidelines under EIA Notification by Ministry of Environment, Forest and Climate Change, Government of India
3. Canter, L.W., Environmental Impact Assessment, McGraw Hill, New York. 1996

**REFERENCE BOOKS:**

1. Lawrence, D.P., Environmental Impact Assessment – Practical solutions to recurrent problems, Wiley-Interscience, New Jersey. 2003
2. Lee N. and George C. 2000. Environmental Assessment in Developing and Transitional Countries. Chichester: Willey
3. World Bank –Source book on EIA ,1999
4. Sam Mannan, Lees' Loss Prevention in the Process Industries, Hazard Identification Assessment and Control, 4th Edition, Butterworth Heineman, 2012.

**P23PEO05**

**BLOCKCHAIN TECHNOLOGIES**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. This course is intended to study the basics of Blockchain technology
2. During this course the learner will explore various aspects of Blockchain technology like application in various domains.
3. By implementing, learners will have idea about private and public Blockchain, and smart contract

**UNIT I INTRODUCTION OF CRYPTOGRAPHY AND BLOCKCHAIN 9**

Introduction to Blockchain, Blockchain Technology Mechanisms & Networks, Blockchain Origins, Objective of Blockchain, Blockchain Challenges, Transactions and Blocks, P2P Systems, Keys as Identity, Digital Signatures, Hashing, and public key cryptosystems, private vs. public Blockchain.

<b>UNIT II</b>	<b>BITCOIN AND CRYPTOCURRENCY</b>	<b>9</b>
Introduction to Bitcoin, The Bitcoin Network, The Bitcoin Mining Process, Mining Developments, Bitcoin Wallets, Decentralization and Hard Forks, Ethereum Virtual Machine (EVM), Merkle Tree, Double-Spend Problem, Blockchain and Digital Currency, Transactional Blocks, Impact of Blockchain Technology on Cryptocurrency.		
<b>UNIT III</b>	<b>INTRODUCTION TO ETHEREUM</b>	<b>9</b>
Introduction to Ethereum, Consensus Mechanisms, Metamask Setup, Ethereum Accounts, Transactions, Receiving Ethers, Smart Contracts.		
<b>UNIT IV</b>	<b>INTRODUCTION TO HYPERLEDGER AND SOLIDITY PROGRAMMING</b>	<b>9</b>
Introduction to Hyperledger, Distributed Ledger Technology & its Challenges, Hyperledger & Distributed Ledger Technology, Hyperledger Fabric, Hyperledger Composer. Solidity - Language of Smart Contracts, Installing Solidity & Ethereum Wallet, Basics of Solidity, Layout of a Solidity Source File & Structure of Smart Contracts, General Value Types.		
<b>UNIT V</b>	<b>BLOCKCHAIN APPLICATIONS</b>	<b>9</b>
Internet of Things, Medical Record Management System, Domain Name Service and Future of Blockchain, Alt Coins.		

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand and explore the working of Blockchain technology
- CO2 :** Analyze the working of Smart Contracts
- CO3:** Understand and analyze the working of Hyperledger
- CO4:** Apply the learning of solidity to build de-centralized apps on Ethereum
- CO5:** Develop applications on Blockchain

**TEXT BOOKS:**

1. Imran Bashir, “Mastering Blockchain: Distributed Ledger Technology, Decentralization, and Smart Contracts Explained”, Second Edition, Packt Publishing, 2018.
2. Narayanan, J. Bonneau, E. Felten, A. Miller, S. Goldfeder, “Bitcoin and Cryptocurrency Technologies: A Comprehensive Introduction” Princeton University Press, 2016

**REFERENCE BOOKS:**

1. Antonopoulos, Mastering Bitcoin, O’Reilly Publishing, 2014. .
2. Antonopoulos and G. Wood, “Mastering Ethereum: Building Smart Contracts and Dapps”, O’Reilly Publishing, 2018.
3. D. Drescher, Blockchain Basics. Apress, 2017.

**P23PEO06**

**DEEP LEARNING**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. Develop and Train Deep Neural Networks.
2. Develop a CNN, R-CNN, Fast R-CNN, Faster-R-CNN, Mask-RCNN for detection and recognition
3. Build and train RNNs, work with NLP and Word Embeddings
4. The internal structure of LSTM and GRU and the differences between them
5. The Auto Encoders for Image Processing

**UNIT I DEEP LEARNING CONCEPTS**

**6**

Fundamentals about Deep Learning. Perception Learning Algorithms. Probabilistic modelling. Early Neural Networks. How Deep Learning different from Machine Learning. Scalars. Vectors. Matrixes, Higher Dimensional Tensors. Manipulating Tensors. Vector Data. Time Series Data. Image Data. Video Data.

**UNIT II NEURAL NETWORKS**

**9**

About Neural Network. Building Blocks of Neural Network. Optimizers. Activation Functions. Loss Functions. Data Pre-processing for neural networks, Feature Engineering. Overfitting and Underfitting. Hyperparameters

**UNIT III CONVOLUTIONAL NEURAL NETWORK**

**10**

About CNN. Linear Time Invariant. Image Processing Filtering. Building a convolutional neural network. Input Layers, Convolution Layers. Pooling Layers. Dense Layers. Backpropagation Through the Convolutional Layer. Filters and Feature Maps. Backpropagation Through the Pooling Layers. Dropout Layers and Regularization. Batch Normalization. Various Activation Functions. Various Optimizers. LeNet, AlexNet, VGG16, ResNet. Transfer Learning with Image Data. Transfer Learning using Inception Oxford VGG Model, Google Inception Model, Microsoft ResNet Model. R-CNN, Fast R-CNN, Faster R-CNN, Mask-RCNN, YOLO

**UNIT IV NATURAL LANGUAGE PROCESSING USING RNN**

**10**

About NLP & its Toolkits. Language Modeling . Vector Space Model (VSM). Continuous Bag of Words (CBOW). Skip-Gram Model for Word Embedding. Part of Speech (PoS) Global Co-occurrence Statistics–based Word Vectors. Transfer Learning. Word2Vec. Global Vectors for Word Representation GloVe. Backpropagation Through Time. Bidirectional RNNs (BRNN) . Long Short Term Memory (LSTM). Bi-directional LSTM. Sequence-to-Sequence Models (Seq2Seq). Gated recurrent unit GRU.

**UNITV DEEP REINFORCEMENT & UNSUPERVISED LEARNING**

**10**

About Deep Reinforcement Learning. Q-Learning. Deep Q-Network (DQN). Policy Gradient Methods. Actor-Critic Algorithm. About Autoencoding. Convolutional Auto Encoding. Variational Auto Encoding. Generative Adversarial Networks. Autoencoders for Feature

Extraction. Auto Encoders for Classification. Denoising Autoencoders. Sparse Autoencoders

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Feature Extraction from Image and Video Data
- CO2 :** Implement Image Segmentation and Instance Segmentation in Images
- CO3:** Implement image recognition and image classification using a pretrained network (Transfer Learning)
- CO4:** Traffic Information analysis using Twitter Data
- CO5:** Autoencoder for Classification & Feature Extraction

**TEXT BOOKS:**

1. Deep Learning A Practitioner’s Approach Josh Patterson and Adam Gibson O’Reilly Media, Inc.2017
2. Learn Keras for Deep Neural Networks, Jojo Moolayil, Apress,2018

**REFERENCE BOOKS:**

1. Deep Learning Projects Using TensorFlow 2, Vinita Silaparasetty, Apress, 2020
2. Deep Learning with Python, FRANÇOIS CHOLLET, MANNING SHELTER ISLAND,2017
3. Pro Deep Learning with TensorFlow, Santanu Pattanayak, Apress,2017

<b>P23PEO07</b>	<b>VIBRATION AND NOISE CONTROL STRATEGIES</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To appreciate the basic concepts of vibration in damped and undamped systems
2. To appreciate the basic concepts of noise, its effect on hearing and related terminology
3. To use the instruments for measuring and analyzing the vibration levels in a body
4. To use the instruments for measuring and analyzing the noise levels in a system
5. To learn the standards of vibration and noise levels and their control techniques

**UNIT I BASICS OF VIBRATION 9**

Introduction – Sources and causes of Vibration-Mathematical Models - Displacement, velocity and Acceleration - Classification of vibration: free and forced vibration, undamped and damped vibration, linear and non-linear vibration - Single Degree Freedom Systems - Vibration isolation - Determination of natural frequencies

**UNIT II BASICS OF NOISE 9**

Introduction - Anatomy of human ear - Mechanism of hearing - Amplitude, frequency, wavelength and sound pressure level - Relationship between sound power, sound intensity and sound pressure level - Addition, subtraction and averaging decibel levels - sound spectra -Types of sound fields - Octave band analysis - Loudness.

**UNIT III INSTRUMENTATION FOR VIBRATION MEASUREMENT 9**

Experimental Methods in Vibration Analysis.- Vibration Measuring Instruments - Selection of Sensors - Accelerometer Mountings - Vibration Exciters - Mechanical, Hydraulic, Electromagnetic and Electrodynamics – Frequency Measuring Instruments -. System Identification from Frequency Response -Testing for resonance and mode shapes

**UNIT IV INSTRUMENTATION FOR NOISE MEASUREMENT AND ANALYSIS 9**

Microphones - Weighting networks - Sound Level meters, its classes and calibration - Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.

**UNITV METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS CONTROL 9**

Specification of Vibration Limits – Vibration severity standards - Vibration as condition Monitoring Tool – Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber – Need for Balancing - Static and Dynamic Balancing machines – Field balancing - Major sources of noise - Noise survey techniques – Measurement technique for vehicular noise - Road vehicles Noise standard – Noise due to construction equipment and domestic appliances – Industrial noise sources and its strategies – Noise control at the source – Noise control along the path – Acoustic Barriers – Noise control at the receiver -- Sound transmission through barriers – Noise reduction Vs Transmission loss - Enclosures

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** apply the basic concepts of vibration in damped and undamped systems
- CO2 :** apply the basic concepts of noise and to understand its effects on systems
- CO3:** select the instruments required for vibration measurement and its analysis
- CO4:** select the instruments required for noise measurement and its analysis.
- CO5:** recognize the noise sources and to control the vibration levels in a body and to control noise under different strategies.

**TEXT BOOKS:**

1. Singiresu S. Rao, “Mechanical Vibrations”, Pearson Education Incorporated, 2017.
2. Graham Kelly. Sand Shashidhar K. Kudari, “Mechanical Vibrations”, Tata McGraw –Hill Publishing Com. Ltd., 2007.
3. Ramamurti. V, “Mechanical Vibration Practice with Basic Theory”, Narosa Publishing House, 2000.

**REFERENCE BOOKS:**

1. William T. Thomson, “Theory of Vibration with Applications”, Taylor & Francis, 2003.
2. G.K. Grover, “Mechanical Vibrations”, Nem Chand and Bros.,Roorkee, 2014.
3. A.G. Ambekar, “Mechanical Vibrations and Noise Engineering”, PHI Learning Pvt. Ltd., 2014.
4. David A. Bies and Colin H. Hansen, “Engineering Noise Control – Theory and

Practice”, Spon Press, London and New York, 2009.

**P23PEO08 ENERGY CONSERVATION AND MANAGEMENT IN L T P C  
DOMESTIC SECTORS**

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To learn the present energy scenario and the need for energy conservation
2. To understand the different measures for energy conservation in utilities.
3. Acquaint students with principle theories, materials, and construction techniques to create energy efficient buildings.
4. To identify the energy demand and bridge the gap with suitable technology for sustainable habitat
5. To get familiar with the energy technology, current status of research and find the ways to optimize a system as per the user requirement

**UNIT I ENERGY SCENARIO 9**

Primary energy resources - Sectorial energy consumption (domestic, industrial and other sectors), Energy pricing, Energy conservation and its importance, Energy Conservation Act-2001 and its features – Energy star rating.

**UNIT II HEATING, VENTILLATION & AIR CONDITIONING 9**

Basics of Refrigeration and Air Conditioning – COP / EER / SEC Evaluation – SPV system design & optimization for Solar Refrigeration.

**UNIT III LIGHTING, COMPUTER, TV 9**

Specification of Luminaries – Types – Efficacy – Selection & Application – Time Sensors – Occupancy Sensors – Energy conservation measures in computer – Television – Electronic devices.

**UNIT IV ENERGY EFFICIENT BUILDINGS 9**

Conventional versus Energy efficient buildings – Landscape design – Envelope heat loss and heat gain – Passive cooling and heating – Renewable sources integration.

**UNITV ENERGY STORAGE TECHNOLOGIES 9**

Necessity & types of energy storage – Thermal energy storage – Battery energy storage, charging and discharging– Hydrogen energy storage & Super capacitors – energy density and safety issues – Applications

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand technical aspects of energy conservation scenario.  
**CO2 :** Energy audit in any type for domestic buildings and suggest the conservation

- measures
- CO3:** Perform building load estimates and design the energy efficient landscape system.
- CO4:** Gain knowledge to utilize an appliance/device sustainably.
- CO5:** Understand the status and current technological advancement in energy storage

**TEXT BOOKS:**

1. Yogi Goswami, Frank Kreith, Energy Efficiency and Renewable energy Handbook, CRC Press, 2016
2. ASHRAE Handbook 2020 – HVAC Systems & Equipment
3. Paolo Bertoldi, Andrea Ricci, Anibal de Almeida, Energy Efficiency in Household Appliances and Lighting, Conference proceedings, Springer, 2001

**REFERENCE BOOKS:**

1. David A. Bainbridge, Ken Haggard, Kenneth L. Haggard, Passive Solar Architecture: Heating, Cooling, Ventilation, Daylighting, and More Using Natural Flows, Chelsea Green Publishing, 2011.
2. Guide book for National Certification Examination for Energy Managers and Energy Auditors (Could be downloaded from [www.energymanagertraining.com](http://www.energymanagertraining.com))
3. Ibrahim Dincer and Mark A. Rosen, Thermal Energy Storage Systems and Applications, John Wiley & Sons 2002.
4. Robert Huggins, Energy Storage: Fundamentals, Materials and Applications, 2nd edition, Springer, 2015

<b>P23PEO09</b>	<b>ADDITIVE MANUFACTURING</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**UNIT I INTRODUCTION 9**

Need - Development - Rapid Prototyping Rapid Tooling – Rapid Manufacturing – Additive Manufacturing. AM Process Chain- Classification – Benefits.

**UNIT II DESIGN FOR ADDITIVE MANUFACTURING 9**

CAD Model Preparation - Part Orientation and Support Structure Generation -Model Slicing - Tool Path Generation Customized Design and Fabrication - Case Studies.

**UNIT III VAT POLYMERIZATION 9**

Stereolithography Apparatus (SLA)- Materials -Process -Advantages Limitations- Applications. Digital Light Processing (DLP) - Materials – Process - Advantages - Applications. Multi Jet Modelling (MJM) - Principles - Process - Materials - Advantages and Limitations.

**UNIT IV MATERIAL EXTRUSION AND SHEET LAMINATION 9**

Fused Deposition Modeling (FDM)- Process-Materials - Applications and Limitations. Sheet Lamination Process: Laminated Object Manufacturing (LOM)- Basic Principle- Mechanism: Gluing or Adhesive Bonding – Thermal Bonding- Materials- Application and Limitation - Bio-Additive Manufacturing Computer Aided Tissue Engineering (CATE) – Case studies

## **POWDER BASED PROCESS**

Selective Laser Sintering (SLS): Process –Mechanism– Typical Materials and Application- Multi Jet Fusion - Basic Principle— Materials- Application and Limitation - Three Dimensional Printing - Materials -Process - Benefits and Limitations. Selective Laser Melting (SLM) and Electron Beam Melting (EBM): Materials – Process - Advantages and Applications. Beam Deposition Process: Laser Engineered Net Shaping (LENS)- Process - Material Delivery - Process Parameters - Materials -Benefits -Applications.

### **UNIT V CASE STUDIES AND OPPORTUNITIES ADDITIVE MANUFACTURING PROCESSES 9**

Education and training - Automobile- pattern and mould - tooling - Building Printing-Bio Printing - medical implants -development of surgical tools Food Printing -Printing Electronics. Business Opportunities and Future Directions - Intellectual Property.

**TOTAL: 45 PERIODS**

### **TEXT BOOKS:**

1. Andreas Gebhardt and Jan-Steffen Hötter “Additive Manufacturing: 3D Printing for Prototyping and Manufacturing”, Hanser publications, United States, 2015, ISBN: 978-1- 56990-582-1.
2. Ian Gibson, David W. Rosen and Brent Stucker “Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing”, 2nd edition, Springer., United States, 2015, ISBN13: 978-1493921126.

### **REFERENCE BOOKS:**

1. Amit Bandyopadhyay and Susmita Bose, “Additive Manufacturing”, 1st Edition, CRC Press., United States, 2015, ISBN-13: 978-1482223590
2. Andreas Gebhardt, “Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing”, Hanser Gardner Publication, Cincinnati., Ohio, 2011, ISBN :9783446425521.
3. Chua C.K., Leong K.F., and Lim C.S., “Rapid prototyping: Principles and applications”, Third edition, World Scientific Publishers, 2010.

<b>P23PEO10</b>	<b>ELECTRIC VEHICLE TECHNOLOGY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

### **UNIT I NEED FOR ELECTRIC VEHICLES 9**

History and need for electric and hybrid vehicles, social and environmental importance of hybrid and electric vehicles, impact of modern drive-trains on energy supplies, comparison of diesel, petrol, electric and hybrid vehicles, limitations, technical challenges

### **UNIT II ELECTRIC VEHICLE ARCHITECHTURE 9**

Electric vehicle types, layout and power delivery, performance – traction motor characteristics, tractive effort, transmission requirements, vehicle performance, energy consumption, Concepts of hybrid electric drive train, architecture of series and parallel hybrid electric drive train, merits and demerits, mild and full hybrids, plug-in hybrid electric vehicles and range extended hybrid electric vehicles, Fuel cell vehicles.

**UNIT III ENERGY STORAGE**

**9**

Batteries – types – lead acid batteries, nickel based batteries, and lithium based batteries, electrochemical reactions, thermodynamic voltage, specific energy, specific power, energy efficiency, Battery modeling and equivalent circuit, battery charging and types, battery cooling, Ultra-capacitors, Flywheel technology, Hydrogen fuel cell, Thermal Management of the PEM fuel cell

**UNIT IV ELECTRIC DRIVES AND CONTROL**

**9**

Types of electric motors – working principle of AC and DC motors, advantages and limitations, DC motor drives and control, Induction motor drives and control, PMSM and brushless DC motor - drives and control , AC and Switch reluctance motor drives and control – Drive system efficiency – Inverters – DC and AC motor speed controllers

**UNIT V DESIGN OF ELECTRIC VEHICLES**

**9**

Materials and types of production, Chassis skate board design, motor sizing, power pack sizing, component matching, Ideal gear box – Gear ratio, torque–speed characteristics, Dynamic equation of vehicle motion, Maximum tractive effort – Power train tractive effort Acceleration performance, rated vehicle velocity – maximum gradability, Brake performance, Electronic control system, safety and challenges in electric vehicles. Case study of Nissan leaf, Toyota Prius, tesla model 3, and Renault Zoe cars.

**TOTAL: 45 PERIODS**

**REFERENCE BOOKS:**

1. Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, 2nd edition CRC Press, 2011.
2. Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004.
3. James Larminie, John Lowry, Electric Vehicle Technology Explained - Wiley, 2003.
4. Ehsani, M, “Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design”, CRC Press, 2005

**P23PEO11**

**NEW PRODUCT DEVELOPMENT**

L	T	P	C
3	0	0	3

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. Applying the principles of generic development process; and understanding the organization structure for new product design and development.
2. Identifying opportunity and planning for new product design and development.
3. Conducting customer need analysis; and setting product specification for new product design and development.
4. Generating, selecting, and testing the concepts for new product design and development.
5. Applying the principles of Industrial design and prototype for new product design and

development.

**UNIT I INTRODUCTION TO PRODUCT DESIGN & DEVELOPMENT 9**

Introduction – Characteristics of Successful Product Development – People involved in Product Design and Development – Duration and Cost of Product Development – The Challenges of Product Development – The Product Development Process – Concept Development: The Front-End Process – Adapting the Generic Product Development Process – Product Development Process Flows – Product Development Organizations.

**UNIT II OPPORTUNITY IDENTIFICATION & PRODUCT PLANNING 9**

Opportunity Identification: Definition – Types of Opportunities – Tournament Structure of Opportunity Identification – Effective Opportunity Tournaments – Opportunity Identification Process – Product Planning: Four types of Product Development Projects – The Process of Product Planning.

**UNIT III IDENTIFYING CUSTOMER NEEDS & PRODUCT SPECIFICATIONS 9**

Identifying Customer Needs: The Importance of Latent Needs – The Process of Identifying Customer Needs. Product Specifications: Definition – Time of Specifications Establishment – Establishing Target Specifications – Setting the Final Specifications.

**UNIT IV CONCEPT GENERATION, SELECTION & TESTING 9**

Concept Generation: Activity of Concept Generation – Structured Approach – Five step method of Concept Generation. Concept Selection: Methodology – Concept Screening and Concepts Scoring. Concept testing: Seven Step activities of concept testing.

**UNIT V INDUSTRIAL DESIGN & PROTOTYPING 9**

Industrial Design: Need and Impact–Industrial Design Process. Prototyping – Principles of Prototyping – Prototyping Technologies – Planning for Prototypes

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Apply the principles of generic development process; and understand the organization structure for new product design and development.
- CO2 :** Identify opportunity and plan for new product design and development.
- CO3:** Conduct customer need analysis; and set product specification for new product design and development.
- CO4:** Generate, select, and test the concepts for new product design and development.
- CO5:** Apply the principles of Industrial design and prototype for design and develop new products.

**TEXT BOOKS:**

1. Ulrich K.T., Eppinger S. D. and Anita Goyal, “Product Design and Development “McGraw-Hill Education; 7 edition, 2020.

**REFERENCE BOOKS:**

1. Belz A., 36-Hour Course: “Product Development” McGraw-Hill, 2010.
2. Rosenthal S., “Effective Product Design and Development”, Business One Orwin, Homewood, 1992, ISBN1-55623-603-4.
3. Pugh, S., “Total Design Integrated Methods for Successful Product Engineering”, Addison Wesley Publishing, 1991, ISBN0-202-41639-5.
4. Chitale, A. K. and Gupta, R. C., Product Design and Manufacturing, PHI Learning, 2013.
5. Jamnia, A., Introduction to Product Design and Development for Engineers, CRC Press, 2018.

**P23PEO12****SUSTAINABLE MANAGEMENT**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide students with fundamental knowledge of the notion of corporate sustainability.
2. To determine how organizations impacts on the environment and socio-technical systems, the relationship between social and environmental performance and competitiveness, the approaches and methods

**UNIT I MANAGEMENT OF SUSTAINABILITY****9**

Management of sustainability -rationale and political trends: An introduction to sustainability management, International and European policies on sustainable development, theoretical pillars in sustainability management studies.

**UNIT II CORPORATE SUSTAINABILITY AND RESPONSIBILITY****9**

Corporate sustainability parameter, corporate sustainability institutional framework, integration of sustainability into strategic planning and regular business practices, fundamentals of stakeholder engagement.

**UNIT III SUSTAINABILITY MANAGEMENT: STRATEGIES AND APPROACHES****9**

Corporate sustainability management and competitiveness: Sustainability-oriented corporate strategies, markets and competitiveness, Green Management between theory and practice, Sustainable Consumption and Green Marketing strategies, Environmental regulation and strategic postures; Green Management approaches and tools; Green engineering: clean technologies and innovation processes; Sustainable Supply Chain Management and Procurement.

**UNIT IV SUSTAINABILITY AND INNOVATION****9**

Socio-technical transitions and sustainability, Sustainable entrepreneurship, Sustainable pioneers in green market niches, Smart communities and smart specializations.

**UNIT V SUSTAINABLE MANAGEMENT OF RESOURCES,  
COMMODITIES AND COMMONS**

**9**

Energy management, Water management, Waste management, Wild Life Conservation, Emerging trends in sustainable management, Case Studies.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** An understanding of sustainability management as an approach to aid in evaluating and minimizing environmental impacts while achieving the expected social impact.
- CO2 :** An understanding of corporate sustainability and responsible Business Practices
- CO3:** Knowledge and skills to understand, to measure and interpret sustainability performances.
- CO4:** Knowledge of innovative practices in sustainable business and community management
- CO5:** Deep understanding of sustainable management of resources and commodities

**REFERENCE BOOKS:**

1. Daddi, T., Iraldo, F., Testa, Environmental Certification for Organizations and Products: Management, 2015
2. Christian N. Madu, Handbook of Sustainability Management 2012
3. Petra Molthan-Hill, The Business Student's Guide to Sustainable Management: Principles and Practice, 2014
4. Margaret Robertson, Sustainability Principles and Practice, 2014
5. Peter Rogers, An Introduction to Sustainable Development, 2006

**P23PEO13 MICRO AND SMALL BUSINESS MANAGEMENT**

L	T	P	C
3	0	0	3

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To familiarize students with the theory and practice of small business management.
2. To learn the legal issues faced by small business and how they impact operations.

**UNIT I INTRODUCTION TO SMALL BUSINESS**

**9**

Creation, Innovation, entrepreneurship and small business - Defining Small Business –Role of Owner – Manager – government policy towards small business sector –elements of entrepreneurship –evolution of entrepreneurship –Types of Entrepreneurship – social, civic, corporate - Business life cycle - barriers and triggers to new venture creation – process to assist start ups – small business and family business.

**UNIT II SCREENING THE BUSINESS OPPORTUNITY AND  
FORMULATING THE BUSINESS PLAN**

**9**

Concepts of opportunity recognition; Key factors leading to new venture failure; New venture

screening process; Applying new venture screening process to the early stage small firm Role planning in small business – importance of strategy formulation – management skills for small business creation and development.

### **UNIT III BUILDING THE RIGHT TEAM AND MARKETING STRATEGY 9**

Management and Leadership – employee assessments – Tuckman’s stages of group development - The entrepreneurial process model - Delegation and team building - Comparison of HR management in small and large firms - Importance of coaching and how to apply a coaching model. Marketing within the small business - success strategies for small business marketing - customer delight and business generating systems, - market research, - assessing market performance- sales management and strategy - the marketing mix and marketing strategy.

### **UNIT IV FINANCING SMALL BUSINESS 9**

Main sources of entrepreneurial capital; Nature of ‘bootstrap’ financing - Difference between cash and profit - Nature of bank financing and equity financing - Funding-equity gap for small firms. Importance of working capital cycle - Calculation of break-even point - Power of gross profit margin- Pricing for profit - Credit policy issues and relating these to cash flow management and profitability.

### **UNIT V VALUING SMALL BUSINESS AND CRISIS MANAGEMENT 9**

Causes of small business failure - Danger signals of impending trouble - Characteristics of poorly performing firms - Turnaround strategies - Concept of business valuation - Different valuation measurements - Nature of goodwill and how to measure it - Advantages and disadvantages of buying an established small firm - Process of preparing a business for sale.

**TOTAL: 45 PERIODS**

#### **COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Familiarise the students with the concept of small business
- CO2 :** In depth knowledge on small business opportunities and challenges
- CO3:** Ability to devise plans for small business by building the right skills and marketing strategies
- CO4:** Identify the funding source for small start ups
- CO5:** Business evaluation for buying and selling of small firms

#### **REFERENCE BOOKS:**

1. Hankinson,A.(2000). “The key factors in the profile of small firm owner-managers that influence business performance. The South Coast Small Firms Survey, 1997-2000.” Industrial and Commercial Training 32(3):94-98.
2. Parker,R.(2000). “Small is not necessarily beautiful: An evaluation of policy support for small and medium-sized enterprise in Australia.” Australian Journal of Political Science 35(2):239- 253.
3. Journal articles on SME’s.

**P23PEO14**

**INTELLECTUAL PROPERTY RIGHTS**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand intellectual property rights and its valuation.

**UNIT I INTRODUCTION**

**9**

Intellectual property rights - Introduction, Basic concepts, Patents, Copyrights, Trademarks, Trade Secrets, Geographic Indicators; Nature of Intellectual Property, Technological Research, Inventions and Innovations, History - the way from WTO to WIPO, TRIPS.

**UNIT II PROCESS**

**9**

New Developments in IPR, Procedure for grant of Patents, TM, GIs, Patenting under Patent Cooperation Treaty, Administration of Patent system in India, Patenting in foreign countries.

**UNIT III STATUTES**

**9**

International Treaties and conventions on IPRs, The TRIPs Agreement, PCT Agreement, The Patent Act of India, Patent Amendment Act (2005), Design Act, Trademark Act, Geographical Indication Act, Bayh- Dole Act and Issues of Academic Entrepreneurship.

**UNIT IV STRATEGIES IN INTELLECTUAL PROPERTY**

**9**

Strategies for investing in R&D, Patent Information and databases, IPR strength in India, Traditional Knowledge, Case studies.

**UNITV MODELS**

**9**

The technologies Know-how, concept of ownership, Significance of IP in Value Creation, IP Valuation and IP Valuation Models, Application of Real Option Model in Strategic Decision Making, Transfer and Licensing

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understanding of intellectual property and appreciation of the need to protect it
- CO2 :** Awareness about the process of patenting
- CO3:** Understanding of the statutes related to IPR
- CO4:** Ability to apply strategies to protect intellectual property
- CO5:** Ability to apply models for making strategic decisions related to IPR

**REFERENCE BOOKS:**

1. V. Sople Vinod, Managing Intellectual Property by (Prentice hall of India Pvt.Ltd), 2006.
2. Intellectual Property rights and copyrights, EssEss Publications.

3. Primer, R. Anita Rao and Bhanoji Rao, Intellectual Property Rights, Lastain Book company.
4. Edited by Derek Bosworth and Elizabeth Webster, The Management of Intellectual Property, Edward Elgar Publishing Ltd., 2006.
5. WIPO Intellectual Property Hand book.

**P23PEO15**

**ETHICAL MANAGEMENT**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To help students develop knowledge and competence in ethical management and decision making in organizational contexts.

**UNIT I ETHICS AND SOCIETY 9**

Ethical Management- Definition, Motivation, Advantages-Practical implications of ethical management. Managerial ethics, professional ethics, and social Responsibility-Role of culture and society's expectations- Individual and organizational responsibility to society and the community

**UNIT II ETHICAL DECISION MAKING AND MANAGEMENT IN A CRISIS 9**

Managing in an ethical crisis, the nature of a crisis, ethics in crisis management, discuss case studies, analyze real-world scenarios, develop ethical management skills, knowledge, and competencies. Proactive crisis management.

**UNIT III STAKEHOLDERS IN ETHICAL MANAGEMENT 9**

Stakeholders in ethical management, identifying internal and external stakeholders, nature of stakeholders, ethical management of various kinds of stakeholders: customers (product and service issues), employees (leadership, fairness, justice, diversity) suppliers, collaborators, business, community, the natural environment (the sustainability imperative, green management, Contemporary issues).

**UNIT IV INDIVIDUAL VARIABLES IN ETHICAL MANAGEMENT 9**

Understanding individual variables in ethics, managerial ethics, concepts in ethical psychology-ethical awareness, ethical courage, ethical judgment, ethical foundations, ethical emotions/intuitions/intensity. Utilization of these concepts and competencies for ethical decision-making and management.

**UNITV PRACTICAL FIELD-GUIDE, TECHNIQUES AND SKILLS 9**

Ethical management in practice, development of techniques and skills, navigating challenges and dilemmas, resolving issues and preventing unethical management proactively. Role modelling and creating a culture of ethical management and human flourishing.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Role modelling and influencing the ethical and cultural context.
- CO2 :** Respond to ethical crises and proactively address potential crises situations

- CO3:** Understand and implement stakeholder management decisions.  
**CO4:** Develop the ability, knowledge, and skills for ethical management.  
**CO5:** Develop practical skills to navigate, resolve and thrive in management situations

**REFERENCE BOOKS:**

1. Brad Agle, Aaron Miller, Bill O’ Rourke, The Business Ethics Field Guide: the essential companion to leading your career and your company, 2016.
2. Steiner & Steiner, Business, Government & Society: A managerial Perspective, 2011.
3. Lawrence & Weber, Business and Society: Stakeholders, Ethics, Public Policy, 2020.

**P23PEO16**

**SECURITY PRACTICES**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To learn the core fundamentals of system and web security concepts
2. To have through understanding in the security concepts related to networks
3. To deploy the security essentials in IT Sector
4. To be exposed to the concepts of Cyber Security and cloud security
5. To perform a detailed study of Privacy and Storage security and related Issues

**UNIT I SYSTEM SECURITY**

**9**

Model of network security – Security attacks, services and mechanisms – OSI security architecture -A Cryptography primer- Intrusion detection system- Intrusion Prevention system - Security web applications- Case study: OWASP - Top 10 Web Application Security Risks.

**UNIT II NETWORK SECURITY**

**9**

Internet Security - Intranet security- Local Area Network Security - Wireless Network Security - Wireless Sensor Network Security- Cellular Network Security - Mobile security - IOT security - Case Study - Kali Linux.

**UNIT III SECURITY MANAGEMENT**

**9**

Information security essentials for IT Managers- Security Management System - Policy Driven System Management- IT Security - Online Identity and User Management System. Case study: Metasploit

**UNIT IV CYBER SECURITY AND CLOUD SECURITY**

**9**

Cyber Forensics- Disk Forensics – Network Forensics – Wireless Forensics – Database Forensics – Malware Forensics – Mobile Forensics – Email Forensics- Best security practices for automate Cloud infrastructure management – Establishing trust in IaaS, PaaS, and SaaS Cloud types. Case study: DVWA

**UNITV PRIVACY AND STORAGE SECURITY**

**9**

Privacy on the Internet - Privacy Enhancing Technologies - Personal privacy Policies - Detection of Conflicts in security policies- privacy and security in environment monitoring systems. Storage Area Network Security - Storage Area Network Security Devices - Risk management - Physical

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand the core fundamentals of system security
- CO2 :** Apply the security concepts to wired and wireless networks
- CO3:** Implement and Manage the security essentials in IT Sector
- CO4:** Explain the concepts of Cyber Security and Cyber forensics
- CO5:** Be aware of Privacy and Storage security Issues.

**REFERENCE BOOKS:**

1. John R. Vacca, Computer and Information Security Handbook, Third Edition, Elsevier 2017
2. Michael E. Whitman, Herbert J. Mattord, Principles of Information Security, Seventh Edition, Cengage Learning, 2022
3. Richard E. Smith, Elementary Information Security, Third Edition, Jones and Bartlett Learning, 2019
4. Mayor, K.K.Mookhey, Jacopo Cervini, Fairuzan Roslan, Kevin Beaver, Metasploit Toolkit for Penetration Testing, Exploit Development and Vulnerability Research, Syngress publications, Elsevier, 2007. ISBN : 978-1-59749-074-0.
5. John Sammons, "The Basics of Digital Forensics- The Primer for Getting Started in Digital Forensics", Syngress, 2012
6. Cory Altheide and Harlan Carvey, "Digital Forensics with Open Source Tools",2011 Syngress, ISBN: 9781597495875.
7. Siani Pearson, George Yee "Privacy and Security for Cloud Computing" Computer Communications and Networks, Springer, 2013.

**P23PEO17**

**CLOUD COMPUTING TECHNOLOGIES**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To gain expertise in Virtualization, Virtual Machines and deploy practical virtualization solution
2. To understand the architecture, infrastructure and delivery models of cloud computing.
3. To explore the roster of AWS services and illustrate the way to make applications in AWS
4. To gain knowledge in the working of Windows Azure and Storage services offered by Windows Azure
5. To develop the cloud application using various programming model of Hadoop and Aneka

**UNIT I VIRTUALIZATION AND VIRTUALIZATION INFRASTRUCTURE 9**

Basics of Virtual Machines - Process Virtual Machines – System Virtual Machines –Emulation – Interpretation – Binary Translation - Taxonomy of Virtual Machines. Virtualization –Management

Virtualization — Hardware Maximization – Architectures – Virtualization Management – Storage Virtualization – Network Virtualization- Implementation levels of virtualization – virtualization structure – virtualization of CPU, Memory and I/O devices – virtual clusters and Resource Management – Virtualization for data center automation

**UNIT II CLOUD PLATFORM ARCHITECTURE 9**

Cloud Computing: Definition, Characteristics - Cloud deployment models: public, private, hybrid, community – Categories of cloud computing: Everything as a service: Infrastructure, platform, software- A Generic Cloud Architecture Design – Layered cloud Architectural Development – Architectural Design Challenges

**UNIT III AWS CLOUD PLATFORM - IAAS 9**

Amazon Web Services: AWS Infrastructure- AWS API- AWS Management Console - Setting up AWS Storage - Stretching out with Elastic Compute Cloud - Elastic Container Service for Kubernetes- AWS Developer Tools: AWS Code Commit, AWS Code Build, AWS Code Deploy, AWS Code Pipeline, AWS code Star - AWS Management Tools: Cloud Watch, AWS Auto Scaling, AWS control Tower, Cloud Formation, Cloud Trail, AWS License Manager

**UNIT IV PAAS CLOUD PLATFORM 9**

Windows Azure: Origin of Windows Azure, Features, The Fabric Controller – First Cloud APP in Windows Azure- Service Model and Managing Services: Definition and Configuration, Service runtime API- Windows Azure Developer Portal- Service Management API- Windows Azure Storage Characteristics-Storage Services- REST API- Blops

**UNITV PROGRAMMING MODEL 9**

Introduction to Hadoop Framework - Mapreduce, Input splitting, map and reduce functions, specifying input and output parameters, configuring and running a job –Developing Map Reduce Applications - Design of Hadoop file system –Setting up Hadoop Cluster- Aneka: Cloud Application Platform, Thread Programming, Task Programming and Map-Reduce Programming in Aneka

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Employ the concepts of virtualization in the cloud computing
- CO2 :** Identify the architecture, infrastructure and delivery models of cloud computing
- CO3:** Develop the Cloud Application in AWS platform
- CO4:** Apply the concepts of Windows Azure to design Cloud Application
- CO5:** Develop services using various Cloud computing programming models.

**REFERENCE BOOKS:**

1. Bernard Golden, Amazon Web Service for Dummies, John Wiley & Sons, 2013.
2. Raoul Alongi, AWS: The Most Complete Guide to Amazon Web Service from Beginner to Advanced Level, Amazon Asia- Pacific Holdings Private Limited, 2019.
3. Sriram Krishnan, Programming: Windows Azure, O'Reilly,2010.

4. Rajkumar Buyya, Christian Vacchiola, S.Thamarai Selvi, Mastering Cloud Computing , MCGraw Hill Education (India) Pvt. Ltd., 2013.
5. Danielle Ruest, Nelson Ruest, —Virtualization: A Beginner’s Guidell, McGraw-Hill Osborne Media, 2009.
6. Jim Smith, Ravi Nair , "Virtual Machines: Versatile Platforms for Systems and Processes", Elsevier/Morgan Kaufmann, 2005.
7. John W.Rittinghouse and James F.Ransome, "Cloud Computing: Implementation, Management, and Security", CRC Press, 2010.
8. Toby Velte, Anthony Velte, Robert Elsenpeter, "Cloud Computing, A Practical Approach", McGraw-Hill Osborne Media, 2009.
9. Tom White, "Hadoop: The Definitive Guide", Yahoo Press, 2012.

**P23PEO18**

**DESIGN THINKING**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To provide a sound knowledge in UI & UX
2. To understand the need for UI and UX
3. Research Methods used in Design
4. Tools used in UI & UX
5. Creating a wireframe and prototype

**UNIT I UX LIFECYCLE TEMPLATE**

**9**

Introduction. A UX process lifecycle template. Choosing a process instance for your project. The system complexity space. Meet the user interface team. Scope of UX presence within the team. More about UX lifecycles. Business Strategy. Value Innovation. Validated User Research. Killer UX Design. The Blockbuster Value Proposition. What Is a Value Proposition?.

**UNIT II CONTEXTUAL INQUIRY**

**9**

The system concept statement. User work activity data gathering. Look for emotional aspects of work practice. Abridged contextual inquiry process. Data-driven vs. model-driven inquiry. Organizing concepts: work roles and flow model. Creating and managing work activity notes. Constructing your work activity affinity diagram (WAAD). Abridged contextual analysis process. History of affinity diagrams.

**UNIT III DESIGN THINKING, IDEATION, AND SKETCHING**

**9**

Design-informing models: second span of the bridge . Some general “how to” suggestions. A New example domain: slideshow presentations. User models. Usage models. Work environment models. Barrier summaries. Model consolidation. Protecting your sources. Abridged methods for design-informing models extraction. Design paradigms. Design thinking. Design perspectives. User personas. Ideation. Sketching

**UNIT IV UX GOALS, METRICS, AND TARGETS**

**9**

Introduction. UX goals. UX target tables. Work roles, user classes, and UX goals. UX measures. Measuring instruments. UX metrics. Baseline level. Target level. Setting levels. Observed results.

Practical tips and cautions for creating UX targets. How UX targets help manage the user experience engineering process.

**UNITV ANALYSING USER EXPERIENCE**

**9**

Sharpening Your Thinking Tools. UX Research and Strength of Evidence. Agile Personas. How to Prioritize Usability Problems. Creating Insights, Hypotheses and Testable Design Ideas. How to Manage Design Projects with User Experience Metrics. Two Measures that Will Justify Any Design Change. Evangelizing UX Research. How to Create a User Journey Map. Generating Solutions to Usability Problems. Building UX Research Into the Design Studio Methodology. Dealing with Common objections to UX Research. The User Experience Debrief Meeting. Creating a User Experience Dashboard

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Build UI for user Applications
- CO2 :** Use the UI Interaction behaviors and principles
- CO3:** Evaluate UX design of any product or application
- CO4:** Demonstrate UX Skills in product development
- CO5:** Implement Sketching principles

**REFERENCE BOOKS:**

1. UX for Developers: How to Integrate User-Centered Design Principles Into Your Day-to-Day Development Work, Westley Knight. Apress, 2018
2. The UX Book: Process and Guidelines for Ensuring a Quality User Experience, Rex Hartson, Pardha Pyla. Morgan Kaufmann, 2012
3. UX Fundamentals for Non-UX Professionals: User Experience Principles for Managers, Writers, Designers, and Developers, Edward Stull. Apress, 2018
4. Lean UX: Designing Great Products with Agile Teams, Gothelf, Jeff, Seiden, and Josh. O'Reilly Media, 2016
5. Designing UX: Prototyping: Because Modern Design is Never Static, Ben Coleman, and Dan Goodwin. SitePoint, 2017

**P23PEO19**

**PRINCIPLES OF MULTIMEDIA**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To get familiarity with gamut of multimedia and its significance
2. To acquire knowledge in multimedia components.
3. To acquire knowledge about multimedia tools and authoring.
4. To acquire knowledge about multimedia tools and authoring.
5. To acquire knowledge about multimedia tools and authoring.

## **UNIT I INTRODUCTION**

9

Introduction to Multimedia – Characteristics of Multimedia Presentation – Multimedia Components Promotion of Multimedia Based Components – Digital Representation – Media and Data Streams Multimedia Architecture – Multimedia Documents, Multimedia Tasks and Concerns, Production, sharing and distribution, Hypermedia, WWW and Internet, Authoring, Multimedia over wireless and mobile networks

1. Flipped classroom on media Components.
2. External learning – Interactive presentation.

### **Suggested Evaluation Methods:**

1. Tutorial – Handling media components
2. Quizzes on different types of data presentation.

## **UNIT II ELEMENTS OF MULTIMEDIA**

9

Text-Types, Font, Unicode Standard, File Formats, Graphics and Image data representations – data types, file formats, color models; video – color models in video, analog video, digital video, file formats, video display interfaces, 3D video and TV: Audio – Digitization, SNR, SQNR, quantization, audio quality, file formats, MIDI; Animation- Key Frames and Tweening, other Techniques, 2D and 3D Animation.

### **Suggested Activities:**

1. Flipped classroom on different file formats of various media elements.
2. External learning – Adobe after effects, Adobe Media Encoder, Adobe Audition.

### **Suggested Evaluation Methods:**

1. Demonstration on after effects animations.
2. Quizzes on file formats and color models.

## **UNIT III MULTIMEDIA TOOLS**

9

Authoring Tools – Features and Types – Card and Page Based Tools – Icon and Object Based Tools – Time Based Tools – Cross Platform Authoring Tools – Editing Tools – Painting and Drawing Tools – 3D Modeling and Animation Tools – Image Editing Tools – Sound Editing Tools – Digital Movie Tools.

### **Suggested Activities:**

1. Flipped classroom on multimedia tools.
2. External learning – Comparison of various authoring tools.

### **Suggested Evaluation Methods:**

1. Tutorial – Audio editing tool.
2. Quizzes on animation tools.

## **UNIT IV MULTIMEDIA SYSTEMS**

9

Compression Types and Techniques: CODEC, Text Compression: GIF Coding Standards, JPEG standard – JPEG 2000, basic audio compression – ADPCM, MPEG Psychoacoustics, basic Video compression techniques – MPEG, H.26X – Multimedia Database System – User Interfaces – OS Multimedia Support – Hardware Support – Real Time Protocols – Play Back Architectures – Synchronization – Document Architecture – Hypermedia Concepts: Hypermedia Design – Digital Copyrights, Content analysis.

### **Suggested Activities:**

1. Flipped classroom on concepts of multimedia hardware architectures.

2. External learning – Digital repositories and hypermedia design.

**Suggested Evaluation Methods:**

1. Quizzes on multimedia hardware and compression techniques.
2. Tutorial – Hypermedia design.

**UNITV MULTIMEDIA APPLICATIONS FOR THE WEB AND MOBILE PLATFORM 9**

ADDIE Model – Conceptualization – Content Collection – Storyboard–Script Authoring Metaphors – Testing – Report Writing – Documentation. Multimedia for the web and mobile platforms. Virtual Reality, Internet multimedia content distribution, Multimedia Information sharing – social media sharing, cloud computing for multimedia services, interactive cloud gaming. Multimedia information retrieval.

**Suggested Activities:**

1. External learning – Game consoles.
2. External learning – VRML scripting languages.

**Suggested Evaluation Methods:**

1. Demonstration of simple interactive games.
2. Tutorial – Simple VRML program.

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Handle the multimedia elements effectively.
- CO2 :** Articulate the concepts and techniques used in multimedia applications.
- CO3:** Develop effective strategies to deliver Quality of Experience in multimedia applications
- CO4:** Design and implement algorithms and techniques applied to multimedia objects.
- CO5:** Design and develop multimedia applications following software engineering models.

**REFERENCE BOOKS:**

1. Li, Ze-Nian, Drew, Mark, Liu, Jiangchuan, “Fundamentals of Multimedia”, Springer, Third Edition, 2021.
2. Prabhat K.Andleigh, Kiran Thakrar, “MULTIMEDIA SYSTEMS DESIGN”, Pearson Education, 2015.
3. Gerald Friedland, Ramesh Jain, “Multimedia Computing”, Cambridge University Press, 2018. (digital book
4. Ranjan Parekh, “Principles of Multimedia”, Second Edition, McGraw-Hill Education, 2017

**P23PEO20**

**BIG DATA ANALYTICS**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand the basics of big data analytics
2. To understand the search methods and visualisation
3. To learn mining data streams

4. To learn frameworks
5. To gain knowledge on R language

**UNIT I INTRODUCTION TO BIG DATA 9**

Introduction to Big Data Platform – Challenges of Conventional Systems - Intelligent data analysis –Nature of Data - Analytic Processes and Tools - Analysis Vs Reporting - Modern Data Analytic Tools- Statistical Concepts: Sampling Distributions - Re-Sampling - Statistical Inference - Prediction Error

**UNIT II SEARCH METHODS AND VISUALIZATION 9**

Search by simulated Annealing – Stochastic, Adaptive search by Evaluation – Evaluation Strategies –Genetic Algorithm – Genetic Programming – Visualization – Classification of Visual Data Analysis Techniques – Data Types – Visualization Techniques – Interaction techniques –Specific Visual data analysis Techniques.

**UNIT III MINING DATA STREAMS 9**

Introduction To Streams Concepts – Stream Data Model and Architecture - Stream Computing - Sampling Data in a Stream – Filtering Streams – Counting Distinct Elements in a Stream – Estimating Moments – Counting Oneness in a Window – Decaying Window - Real time Analytics Platform(RTAP) Applications - Case Studies - Real Time Sentiment Analysis, Stock Market Predictions

**UNIT IV FRAMEWORKS 9**

Map Reduce – Hadoop, Hive, MapR – Sharding – NoSQL Databases - S3 - Hadoop Distributed File Systems – Case Study- Preventing Private Information Inference Attacks on Social Networks- Grand Challenge: Applying Regulatory Science and Big Data to Improve Medical Device Innovation

**UNITV R LANGUAGE 9**

Overview, Programming structures: Control statements -Operators -Functions -Environment and scope issues -Recursion -Replacement functions, R data structures: Vectors -Matrices and arrays - Lists -Data frames -Classes, Input/output, String manipulations

**TOTAL: 45 PERIODS**

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** To understand the basics of big data analytic
- CO2 :** To understand the search methods and visualization
- CO3:** To learn mining data streams.
- CO4:** To learn frameworks.
- CO5:** To gain knowledge on R language.

**REFERENCE BOOKS:**

1. Michael Berthold, David J. Hand, Intelligent Data Analysis, Springer, 2007.
2. Anand Rajaraman and Jeffrey David Ullman, Mining of Massive Datasets, Cambridge University Press, 3rd edition 2020.
3. Norman Matloff, The Art of R Programming: A Tour of Statistical Software Design, No

- Starch Press, USA, 2011.
4. Bill Franks, Taming the Big Data Tidal Wave: Finding Opportunities in Huge Data Streams with Advanced Analytics, John Wiley & sons, 2012.
  5. Glenn J. Myatt, Making Sense of Data, John Wiley & Sons, 2007.

<b>P23PEO21</b>	<b>INTERNET OF THINGS AND CLOUD</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

### **COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To understand Smart Objects and IoT Architectures
2. To learn about various IOT-related protocols
3. To build simple IoT Systems using Arduino and Raspberry Pi
4. To understand data analytics and cloud in the context of IoT
5. To develop IoT infrastructure for popular applications

#### **UNIT I FUNDAMENTALS OF IoT 9**

Introduction to IoT – IoT definition – Characteristics – IoT Complete Architectural Stack – IoT enabling Technologies – IoT Challenges. Sensors and Hardware for IoT – Hardware Platforms – Arduino, Raspberry Pi, Node MCU. A Case study with any one of the boards and data acquisition from sensors

#### **UNIT II PROTOCOLS FOR IoT 9**

Infrastructure protocol (IPV4/V6/RPL), Identification (URIs), Transport (Wifi, Lifi, BLE), Discovery, Data Protocols, Device Management Protocols. – A Case Study with MQTT/CoAP usage-IoT privacy, security and vulnerability solutions

#### **UNIT III CASE STUDIES/INDUSTRIAL APPLICATIONS 9**

Case studies with architectural analysis: IoT applications – Smart City – Smart Water – Smart Agriculture – Smart Energy – Smart Healthcare – Smart Transportation – Smart Retail – Smart waste management.

#### **UNIT IV CLOUD COMPUTING INTRODUCTION 9**

Introduction to Cloud Computing - Service Model – Deployment Model- Virtualization Concepts – Cloud Platforms – Amazon AWS – Microsoft Azure – Google APIs.

#### **UNITV IoT AND CLOUD 9**

IoT and the Cloud - Role of Cloud Computing in IoT - AWS Components - S3 – Lambda - AWS IoT Core -Connecting a web application to AWS IoT using MQTT- AWS IoT Examples. Security Concerns, Risk Issues, and Legal Aspects of Cloud Computing- Cloud Data Security

**TOTAL: 45 PERIODS**

### **COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Understand the various concept of the IoT and their technologies..
- CO2 :** Develop IoT application using different hardware platforms
- CO3:** Implement the various IoT Protocols
- CO4:** Understand the basic principles of cloud computing
- CO5:** Develop and deploy the IoT application into cloud environment

**REFERENCE BOOKS:**

1. "The Internet of Things: Enabling Technologies, Platforms, and Use Cases", by Pethuru Raj and Anupama C. Raman ,CRC Press, 2017
2. Adrian McEwen, Designing the Internet of Things, Wiley,2013.
3. EMC Education Services, "Data Science and Big Data Analytics: Discovering, Analyzing, Visualizing and Presenting Data", Wiley publishers, 2015.
4. Simon Walkowiak, "Big Data Analytics with R" PackT Publishers, 2016
5. Bart Baesens, "Analytics in a Big Data World: The Essential Guide to Data Science and its Applications", Wiley Publishers, 2015.

**P23PEO22**

**MEDICAL ROBOTICS**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To explain the basic concepts of robots and types of robots
2. To discuss the designing procedure of manipulators, actuators and grippers
3. To impart knowledge on various types of sensors and power sources
4. To explore various applications of Robots in Medicine
5. To impart knowledge on wearable robots

**UNIT I INTRODUCTION TO ROBOTICS**

**9**

Introduction to Robotics, Overview of robot subsystems, Degrees of freedom, configurations and concept of workspace, Dynamic Stabilization

**Sensors and Actuators**

Sensors and controllers, Internal and external sensors, position, velocity and acceleration sensors, Proximity sensors, force sensors Pneumatic and hydraulic actuators, Stepper motor control circuits, End effectors, Various types of Grippers, PD and PID feedback actuator models

**UNIT II MANIPULATORS & BASIC KINEMATICS**

**9**

Construction of Manipulators, Manipulator Dynamic and Force Control, Electronic and pneumatic manipulator, Forward Kinematic Problems, Inverse Kinematic Problems, Solutions of Inverse Kinematic problems

**Navigation and Treatment Planning**

Variable speed arrangements, Path determination – Machinery vision, Ranging – Laser – Acoustic, Magnetic, fiber optic and Tactile sensor

**UNIT III SURGICAL ROBOTS**

**9**

Da Vinci Surgical System, Image guided robotic systems for focal ultrasound based surgical applications, System concept for robotic Tele-surgical system for off-pump, CABG surgery, Urologic applications, Cardiac surgery, Neuro-surgery, Pediatric and General Surgery, Gynecologic Surgery, General Surgery and Nanorobotics. Case Study

**UNIT IV REHABILITATION AND ASSISTIVE ROBOTS****9**

Pediatric Rehabilitation, Robotic Therapy for the Upper Extremity and Walking, Clinical-Based Gait Rehabilitation Robots, Motion Correlation and Tracking, Motion Prediction, Motion Replication. Portable Robot for Tele rehabilitation, Robotic Exoskeletons – Design considerations, Hybrid assistive limb. Case Study

**UNITV WEARABLE ROBOTS****9**

Augmented Reality, Kinematics and Dynamics for Wearable Robots, Wearable Robot technology, Sensors, Actuators, Portable Energy Storage, Human–robot cognitive interaction (cHRI), Human–robot physical interaction (pHRI), Wearable Robotic Communication - case study

**TOTAL: 45 PERIODS****COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** Describe the configuration, applications of robots and the concept of grippers and actuators
- CO2 :** Explain the functions of manipulators and basic kinematics
- CO3:** Describe the application of robots in various surgeries
- CO4:** Design and analyze the robotic systems for rehabilitation
- CO5:** Design the wearable robots

**REFERENCE BOOKS:**

1. Nagrath and Mittal, “Robotics and Control”, Tata McGraw Hill, First edition, 2003
2. Spong and Vidhyasagar, “Robot Dynamics and Control”, John Wiley and Sons, First edition, 2008
3. Fu.K.S, Gonzalez. R.C., Lee, C.S.G, “Robotics, control”, sensing, Vision and Intelligence, Tata McGraw Hill International, First edition, 2008
4. Bruno Siciliano, Oussama Khatib, Springer Handbook of Robotics, 1st Edition, Springer, 2008
5. Shane (S.Q.) Xie, Advanced Robotics for Medical Rehabilitation - Current State of the Art and Recent Advances, Springer, 2016
6. Sashi S Kommu, Rehabilitation Robotics, I-Tech Education and Publishing, 2007
7. Jose L. Pons, Wearable Robots: Biomechatronic Exoskeletons, John Wiley & Sons Ltd, England, 2008
8. Howie Choset, Kevin Lynch, Seth Hutchinson, “Principles of Robot Motion: Theory, Algorithms, and Implementations”, Prentice Hall of India, First edition, 2005
9. Philippe Coiffet, Michel Chirouze, “An Introduction to Robot Technology”, Tata McGraw Hill, First Edition, 1983
10. Jacob Rosen, Blake Hannaford & Richard M Satava, “Surgical Robotics: System Applications & Visions”, Springer 2011
11. Jocelyn Troccaz, Medical Robotics, Wiley, 2012
12. Achim Schweikard, Floris Ernst, Medical Robotics, Springer, 2015

**P23PEO23**

**EMBEDDED AUTOMATION**

**L T P C**  
**3 0 0 3**

**COURSE OBJECTIVES**

The main learning objective of this course is to prepare the students for:

1. To learn about the process involved in the design and development of real-time embedded system
2. To develop the embedded C programming skills on 8-bit microcontroller
3. To study about the interfacing mechanism of peripheral devices with 8-bit microcontrollers
4. To learn about the tools, firmware related to microcontroller programming
5. To build a home automation system

**UNIT I INTRODUCTION TO EMBEDDED C PROGRAMMING 9**

C Overview and Program Structure - C Types, Operators and Expressions - C Control Flow - C Functions and Program Structures - C Pointers And Arrays - FIFO and LIFO - C Structures - Development Tools.

**UNIT II AVR MICROCONTROLLER 9**

ATMEGA 16 Architecture - Nonvolatile and Data Memories - Port System - Peripheral Features : Time Base, Timing Subsystem, Pulse Width Modulation, USART, SPI, Two Wire Serial Interface, ADC, Interrupts - Physical and Operating Parameters

**UNIT III HARDWARE AND SOFTWARE INTERFACING WITH 8-BIT SERIES CONTROLLERS 9**

Lights and Switches - Stack Operation - Implementing Combinational Logic - Expanding I/O - Interfacing Analog To Digital Convertors - Interfacing Digital To Analog Convertors - LED Displays : Seven Segment Displays, Dot Matrix Displays - LCD Displays - Driving Relays - Stepper Motor Interface - Serial EEPROM - Real Time Clock - Accessing Constants Table - Arbitrary Waveform Generation - Communication Links - System Development Tools

**UNIT IV VISION SYSTEM 9**

Fundamentals of Image Processing - Filtering - Morphological Operations - Feature Detection and Matching - Blurring and Sharpening - Segmentation - Thresholding - Contours - Advanced Contour Properties - Gradient - Canny Edge Detector - Object Detection - Background Subtraction.

**UNITV HOME AUTOMATION 9**

Home Automation - Requirements - Water Level Notifier - Electric Guard Dog - Tweeting Bird Feeder - Package Delivery Detector - Web Enabled Light Switch - Curtain Automation - Android Door Lock - Voice Controlled Home Automation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor -Proximity Garage Door Opener - Vision Based Authentic Entry System

**COURSE OUTCOMES:**

At the end of the course the students would be able to

- CO1 :** analyse the 8-bit series microcontroller architecture, features and pin details
- CO2 :** write embedded C programs for embedded system application
- CO3:** design and develop real time systems using AVR microcontrollers
- CO4:** design and develop the systems based on vision mechanism
- CO5:** Design the wearable robots
- CO6:** design and develop a real time home automation system

**REFERENCE BOOKS:**

1. Dhananjay V. Gadre, "Programming and Customizing the AVR Microcontroller", McGraw-Hill, 2001.
2. Joe Pardue, "C Programming for Microcontrollers ", Smiley Micros, 2005.
3. Steven F. Barrett, Daniel J. Pack, "ATMEL AVR Microcontroller Primer : Programming and Interfacing", Morgan & Claypool Publishers, 2012
4. Mike Riley, "Programming Your Home - Automate With Arduino, Android and Your Computer", the Pragmatic Programmers, Llc, 2012
5. Richard Szeliski, "Computer Vision: Algorithms and Applications", Springer, 2011.
6. Kevin P. Murphy, "Machine Learning - a Probabilistic Perspective", the MIT Press Cambridge, Massachusetts, London, 2012

<b>P23PEO24</b>	<b>ENVIRONMENTAL SUSTAINABILITY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>
	<b>UNIT I INTRODUCTION</b>				<b>9</b>
	Valuing the Environment: Concepts, Valuing the Environment: Methods, Property Rights, Externalities, and Environmental Problems				
	<b>UNIT II CONCEPT OF SUSTAINABILITY</b>				<b>9</b>
	Sustainable Development: Defining the Concept, the Population Problem, Natural Resource Economics: An Overview, Energy, Water, Agriculture				
	<b>UNIT III SIGNIFICANCE OF BIODIVERSITY</b>				<b>9</b>
	Biodiversity, Forest Habitat, Commercially Valuable Species, Stationary - Source Local Air Pollution, Acid Rain and Atmospheric Modification, Transportation				
	<b>UNIT IV POLLUTION IMPACTS</b>				<b>9</b>
	Water Pollution, Solid Waste and Recycling, Toxic Substances and Hazardous Wastes, Global Warming				
	<b>UNITV ENVIRONMENTAL ECONOMICS</b>				<b>9</b>
	Development, Poverty, and the Environment, Visions of the Future, Environmental economics and policy by Tom Tietenberg, Environmental Economics				

**TOTAL: 45 PERIODS**

**REFERENCE BOOKS:**

1. Andrew Hoffman, Competitive Environmental Strategy - A Guide for the Changing Business Landscape, Island Press.
2. Stephen Doven, Environment and Sustainability Policy: Creation, Implementation, Evaluation, the Federation Press, 2005
3. Robert Brinkmann., Introduction to Sustainability, Wiley-Blackwell., 2016
4. Niko Roorda., Fundamentals of Sustainable Development, 3rd Edn, Routledge, 2020
5. Bhavik R Bakshi., Sustainable Engineering: Principles and Practice, Cambridge University Press, 2019

**P23PEO25**

**TEXTILE REINFORCED COMPOSITES**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**UNIT I REINFORCEMENTS**

**9**

Introduction – composites –classification and application; reinforcements- fibres and its properties; preparation of reinforced materials and quality evaluation; preforms for various composites

**UNIT II MATRICES**

**9**

Preparation, chemistry, properties and applications of thermoplastic and thermoset resins; mechanism of interaction of matrices and reinforcements; optimization of matrices.

**UNIT III COMPOSITE MANUFACTURING**

**9**

Classification; methods of composites manufacturing for both thermoplastics and thermosets- Hand layup, Filament Winding, Resin transfer moulding, prepregs and autoclave moulding, pultrusion, vacuum impregnation methods, compression moulding; post processing of composites and composite design requirements

**UNIT IV TESTING**

**9**

Fibre volume and weight fraction, specific gravity of composites, tensile, flexural, impact, compression, inter laminar shear stress and fatigue properties of thermoset and thermoplastic composites.

**UNIT V MECHANICS**

**9**

Micro mechanics, macro mechanics of single layer, macro mechanics of laminate, classical lamination theory, failure theories and prediction of inter laminar stresses using at ware

**TOTAL: 45 PERIODS**

**REFERENCE BOOKS:**

1. BorZ.Jang,“Advanced Polymer composites”,ASM International,USA,1994.
2. Carlsson L.A.and Pipes R.B., “Experimental Characterization of advanced composite Materials”,SecondEdition,CRCPress,NewJersey,1996.
3. George LubinandStanley T.Peters, “Handbook of Composites”, Springer Publications,1998.

4. Mel. M. Schwartz, "Composite Materials", Vol. 1 &2, Prentice Hall PTR, New Jersey,1997.
5. RichardM.Christensen,"Mechanics of compositematerials",DoverPublications,2005.
6. Sanjay K. Mazumdar, "Composites Manufacturing: Materials, Product, and Process Engineering",CRCPress,2001

**P23PEO26** **L T P C**  
**NANOCOMPOSITE MATERIALS** **3 0 0 3**

**UNIT I BASICS OF NANOCOMPOSITES** **9**

Nomenclature, Properties, features and processing of nanocomposites. Sample Preparation and Characterization of Structure and Physical properties. Designing, stability and mechanical properties and applications of super hard nanocomposites

**UNIT II METAL BASED NANOCOMPOSITES** **9**

Metal-metal nanocomposites, some simple preparation techniques and their properties. Metal- Oxide or Metal-Ceramic composites, Different aspects of their preparation techniques and their final properties and functionality. Fractal based glass-metal nanocomposites, its designing and fractal dimension analysis. Core-Shell structured nanocomposites

**UNIT III POLYMER BASED NANOCOMPOSITES** **9**

Classification; methods of composites manufacturing for both thermoplastics and thermosets- Hand layup, Filament Winding, Resin transfer moulding, prepregs and autoclave moulding, pultrusion, vacuum impregnation methods, compression moulding; post processing of composites and composite design requirements

**UNIT IV TESTING** **9**

Fibre volume and weight fraction, specific gravity of composites, tensile, flexural, impact, compression, inter laminar shear stress and fatigue properties of thermoset and thermoplastic composites.

**UNITV MECHANICS** **9**

Micro mechanics, macro mechanics of single layer, macro mechanics of laminate, classical lamination theory, failure theories and prediction of inter laminar stresses using at ware

**TOTAL: 45 PERIODS**

**REFERENCE BOOKS:**

1. BorZ.Jang,"Advanced Polymer composites",ASM International,USA,1994.
2. Carlsson L.A.and Pipes R.B., "Experimental Characterization of advanced composite Materials",SecondEdition,CRCPress,NewJersey,1996.
3. George LubinandStanley T.Peters, "Handbook of Composites", Springer Publications,1998
4. Mel. M. Schwartz, "Composite Materials", Vol. 1 &2, Prentice Hall PTR, New Jersey,1997.
5. RichardM.Christensen,"Mechanics of compositematerials",DoverPublications,2005.
6. Sanjay K. Mazumdar, "Composites Manufacturing: Materials, Product, and Process Engineering",CRCPress,2001

<b>P23PEO27</b>	<b>IPR, BIOSAFETY AND ENTREPRENEURSHIP</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**UNIT I IPR 9**

Intellectual property rights – Origin of the patent regime – Early patents act & Indian pharmaceutical industry – Types of patents – Patent Requirements – Application preparation filing and prosecution – Patentable subject matter – Industrial design, Protection of GMO’s IP as a factor in R&D, IP’s of relevance to biotechnology and few case studies.

**UNIT II AGREEMENTS, TREATIES AND PATENT FILING PROCEDURES 9**

History of GATT Agreement – Madrid Agreement – Hague Agreement – WIPO Treaties – Budapest Treaty – PCT – Ordinary – PCT – Conventional – Divisional and Patent of Addition – Specifications – Provisional and complete – Forms and fees Invention in context of “prior art” – Patent databases – Searching International Databases – Country-wise patent searches (USPTO, espacenet(EPO) – PATENT Scope (WIPO) – IPO, etc National & PCT filing procedure – Time frame and cost – Status of the patent applications filed – Precautions while patenting – disclosure/non-disclosure – Financial assistance for patenting – Introduction to existing schemes Patent licensing and agreement Patent infringement – Meaning, scope, litigation, case studies

**UNIT III BIOSAFETY 9**

Introduction – Historical Background – Introduction to Biological Safety Cabinets – Primary Containment for Biohazards – Biosafety Levels – Biosafety Levels of Specific Microorganisms – Recommended Biosafety Levels for Infectious Agents and Infected Animals – Biosafety guidelines – Government of India

**UNIT IV GENETICALLY MODIFIED ORGANISMS 9**

Definition of GMOs & LMOs – Roles of Institutional Biosafety Committee – RCGM – GEAC etc. for GMO applications in food and agriculture – Environmental release of GMOs – Risk Analysis – Risk Assessment – Risk management and communication – Overview of National Regulations and relevant International Agreements including Cartagena Protocol.

**UNITV ENTREPRENEURSHIP DEVELOPMENT 9**

Introduction – Entrepreneurship Concept – Entrepreneurship as a career – Entrepreneurial personality – Characteristics of successful Entrepreneur – Factors affecting entrepreneurial growth – Entrepreneurial Motivation – Competencies – Mobility – Entrepreneurship Development Programmes (EDP) - Launching Of Small Enterprise - Definition, Characteristics – Relationship between small and large units – Opportunities for an Entrepreneurial career – Role of small enterprise in economic development – Problems of small scale industries – Institutional finance to entrepreneurs - Institutional support to entrepreneurs.

**TOTAL: 45 PERIODS**

**REFERENCE BOOKS:**

1. Bouchoux, D.E., “Intellectual Property: The Law of Trademarks, Copyrights, Patents, and Trade Secrets for the Paralegal”, 3rd Edition, Delmar Cengage Learning, 2008..
2. Fleming, D.O. and Hunt, D.L., “Biological Safety: Principles and Practices”, 4th Edition, American Society for Microbiology, 2006.
3. Irish, V., “Intellectual Property Rights for Engineers”, 2nd Edition, The Institution of Engineering and Technology, 2005.
4. Mueller, M.J., “Patent Law”, 3rd Edition, Wolters Kluwer Law & Business, 2009.
- 5 Young, T., “Genetically Modified Organisms and Biosafety: A Background Paper for Decision- Makers and Others to Assist in Consideration of GMO Issues” 1st Edition, World Conservation Union, 2004.
- 6 S.S Khanka, “Entrepreneurial Development”, S.Chand & Company LTD, New Delhi, 2007



